

Intrusion detection in unlabeled data with quarter-sphere Support Vector Machines

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Unsupervised anomaly detection in IDS

- *Main idea:* search for anomalies in the data *without* training on the clean data.
- *Previous work:* (Eskin et al., 2002), (Lazarevic et al., 2003).
- *Advantages:* no need for training, no need for extensive amount of clean data.
- *Problems:* false alarm rates, performance.

Motivation for our work

- Reproduce the state-of-the-art results on the KDD Cup (DARPA '98) dataset (with the main focus on one-class SVM).
- Investigate the methods from the machine learning point of view.
- Investigate the behavior of anomaly detection methods with varying outlier percentages.

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- Investigate the behavior of anomaly detection methods with varying outlier percentages.

Main result: we propose a new anomaly detection technique, a quarter-sphere SVM, which is particularly geared for data used in intrusion detection and is significantly faster than other one-class SVM methods.

KDD Cup data: summary of features

KDD Cup dataset contains the total of 42 features computed for connections of TCP data from the DARPA '98 evaluation.

Source	Sample attributes	Type
Basic connection properties	<code>duration, service, src_bytes, dest_bytes</code>	<code>int, bool, string</code>
Selected content features	<code>logged_in, root_shell, num_shells</code>	<code>int, bool</code>
Time window features	<code>count, srv_count, serror_rate, rerror_rate</code>	<code>int, float</code>
Connection window features	<code>dst_host_count, ...</code>	<code>int, float</code>

KDD Cup data: normalization

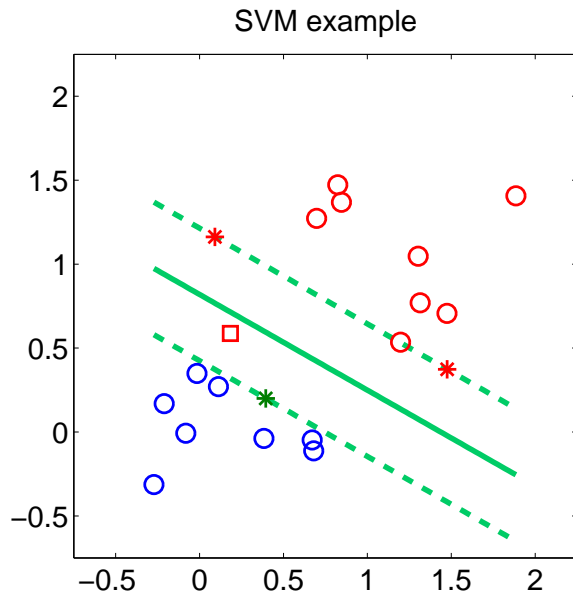
- *Numerical attributes*: replace the values with distance from mean in the number of standard deviations.

$$x_i^{(d)} \leftarrow \frac{|x_i^{(d)} - \hat{\mu}^{(d)}|}{\hat{\sigma}^{(d)}}$$

- *Categorical attributes*: extend the space with $\text{card}^{(d)}$ coordinates; assign the value of $\frac{1}{\text{card}^{(d)}}$ to coordinates matching the attribute's value.

Support Vector Machines (SVM)

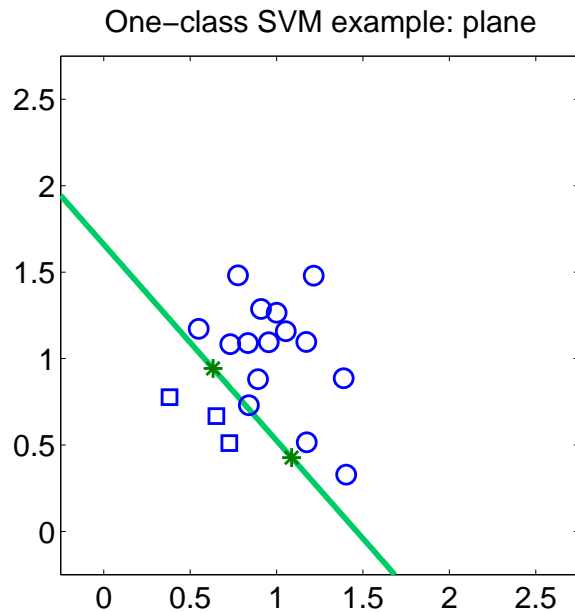
The main idea of SVM: separation of examples of two classes with a hyperplane producing a large margin:



$$\begin{aligned} \min_{\mathbf{w}, \xi, b} \quad & \frac{1}{2} \|\mathbf{w}\|^2 + \frac{C}{l} \sum_{i=1}^l \xi_i \\ \text{subject to} \quad & y_i ((\mathbf{w} \cdot \mathbf{x}_i) + b) \geq 1 - \xi_i, \\ & \xi_i \geq 0. \end{aligned}$$

One-class SVM: plane formulation

The main idea of the plane one-class SVM: separate data from the origin with a hyperplane:

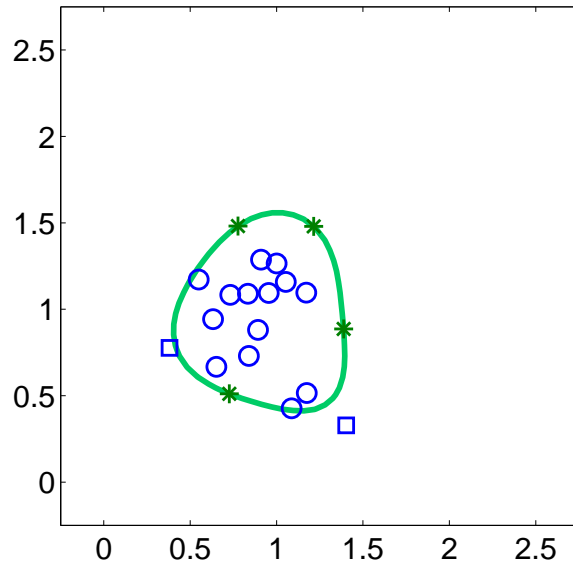


$$\begin{aligned} \min_{\mathbf{w}, \xi, b} \quad & \frac{1}{2} \|\mathbf{w}\|^2 + \sum_{i=1}^l \xi_i - \nu \rho \\ \text{subject to} \quad & (\mathbf{w} \cdot \mathbf{x}_i) + b \geq \rho - \xi_i, \\ & \xi_i \geq 0. \end{aligned}$$

One-class SVM: sphere formulation

The main idea of the sphere one-class SVM: fit a hypersphere around the data:

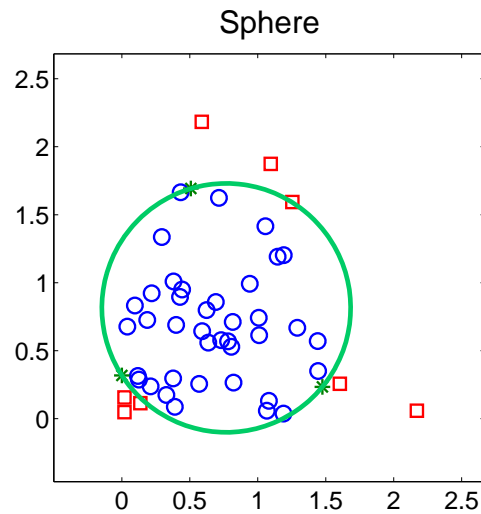
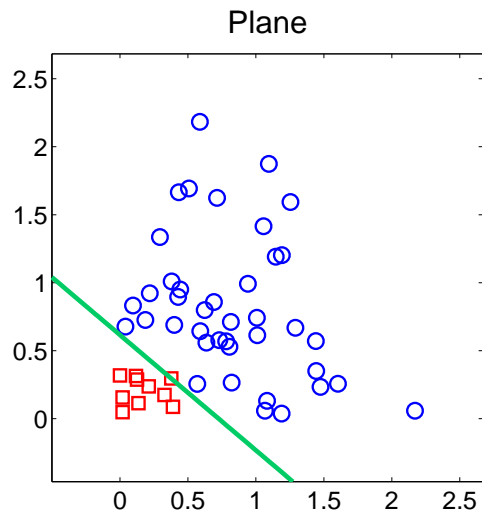
One-class SVM example: sphere



$$\begin{aligned} & \min_{\mathbf{c}, \zeta, R^2} && R^2 + \frac{1}{\nu l} \sum_{i=1}^l \zeta_i \\ & \text{subject to} && \|\mathbf{c} - \mathbf{x}_i\|^2 \leq R^2 + \zeta_i, \\ & && \zeta_i \geq 0. \end{aligned}$$

One-class SVM on non-negative data

Previous methods

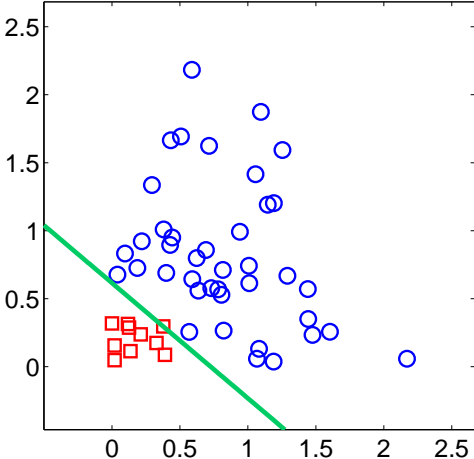


One-class SVM on non-negative data

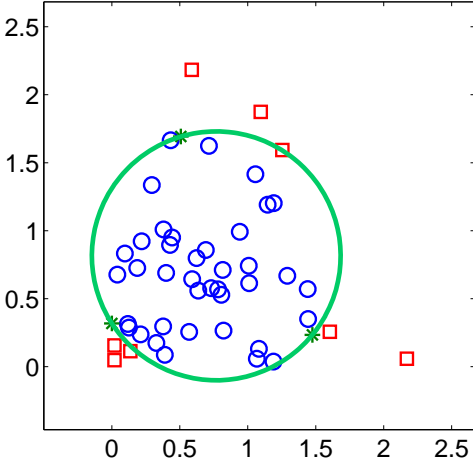
Previous methods

New method

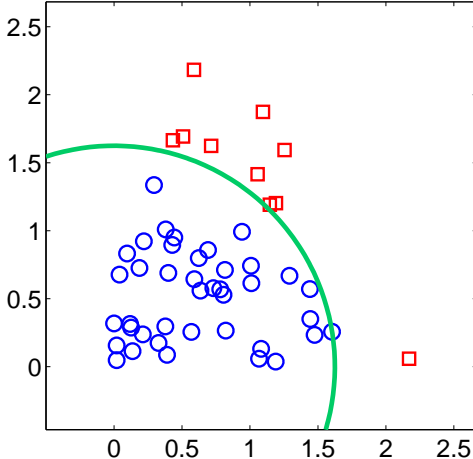
Plane



Sphere



Quarter-sphere

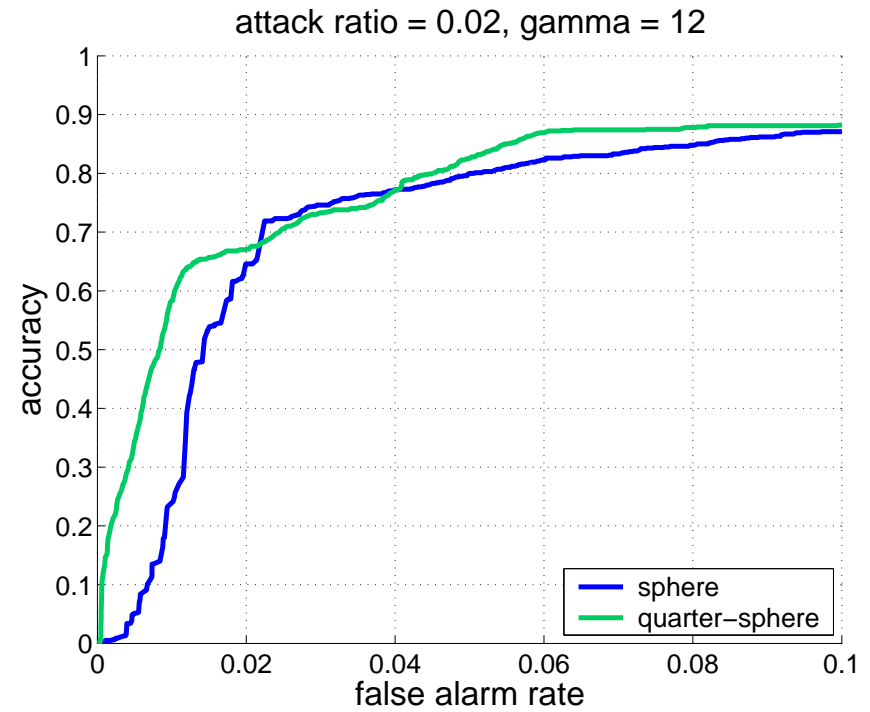
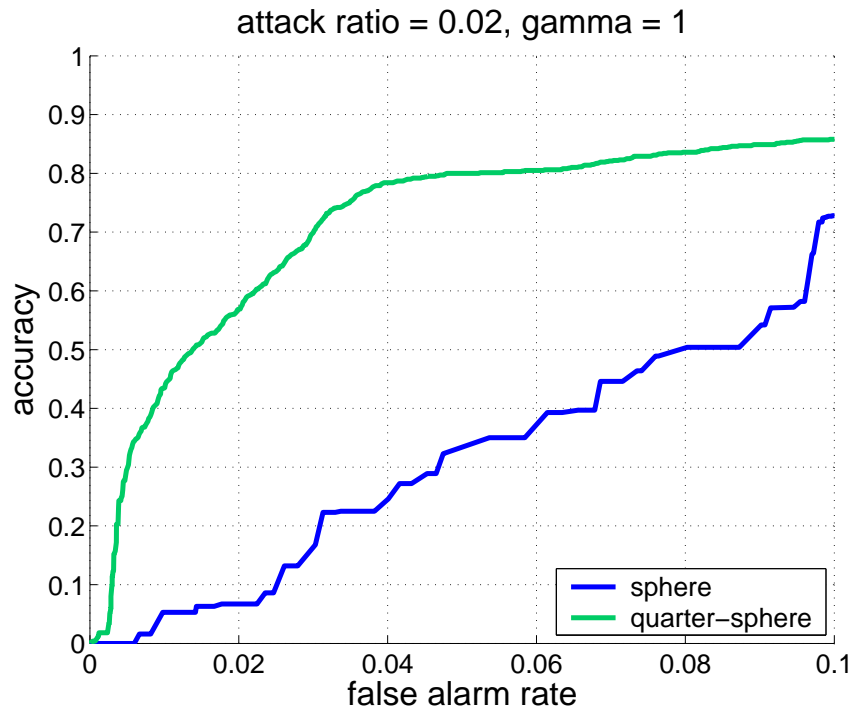


Quarter-sphere SVM: dual formulation

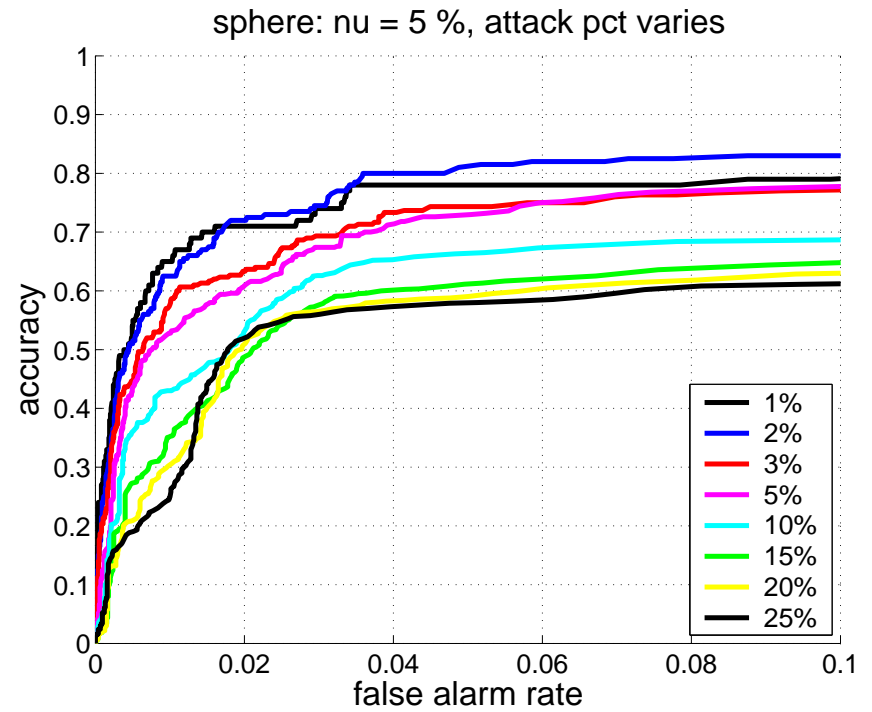
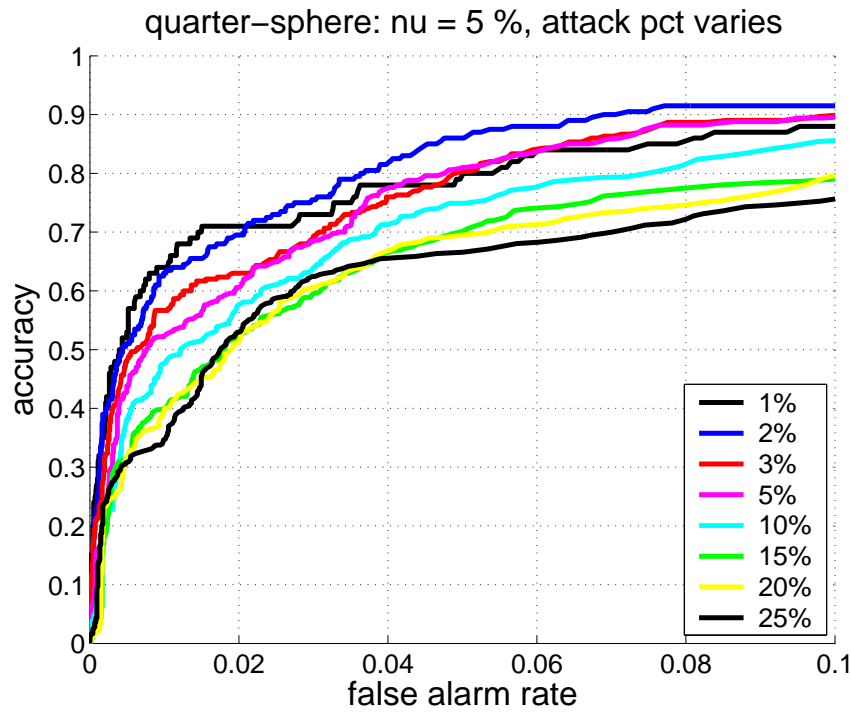
Algorithmically, the following *linear program* must be solved to apply a quarter-sphere SVM:

$$\begin{aligned} & \max_{\alpha} && \sum_{i=1}^l \alpha_i k(\mathbf{x}_i, \mathbf{x}_i), \\ & \text{subject to} && 0 \leq \alpha_i \leq C, \quad i = 1, \dots, l, \\ & && \sum_{i=1}^l \alpha_i = 1. \end{aligned}$$

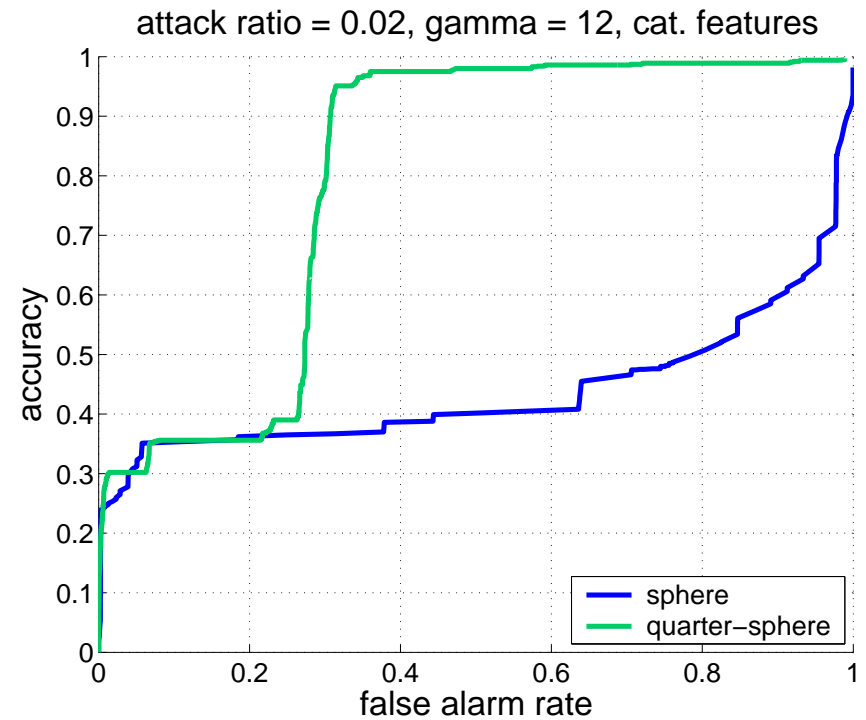
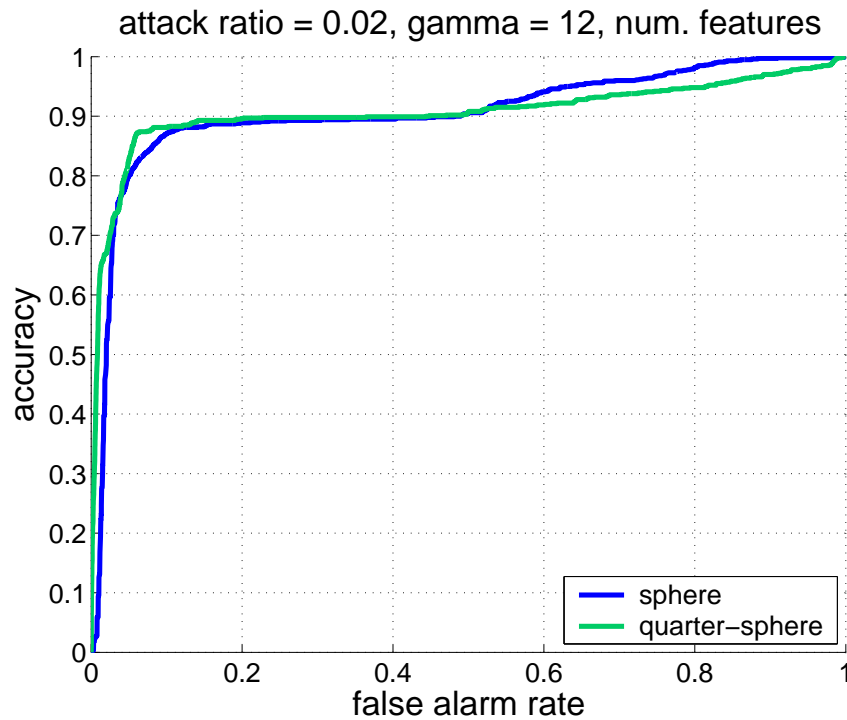
Results: Quarter-sphere vs. Sphere



Results: varying attack percentage



Results: numerical vs. categorical features



Conclusions

- Designing special-purpose anomaly detection techniques, suited for the data arising in IDS, can significantly decrease false alarm rates.
- What is most needed for the success of anomaly detection:
 - Precise understanding of *how* different mechanisms of anomaly detection work on the data arising in IDS.
 - Critical analysis with respect to *robustness*, i.e. operation under conditions that anomalies are not rare or their impact can significantly tilt the decision toward the anomaly.