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Discussion Paper

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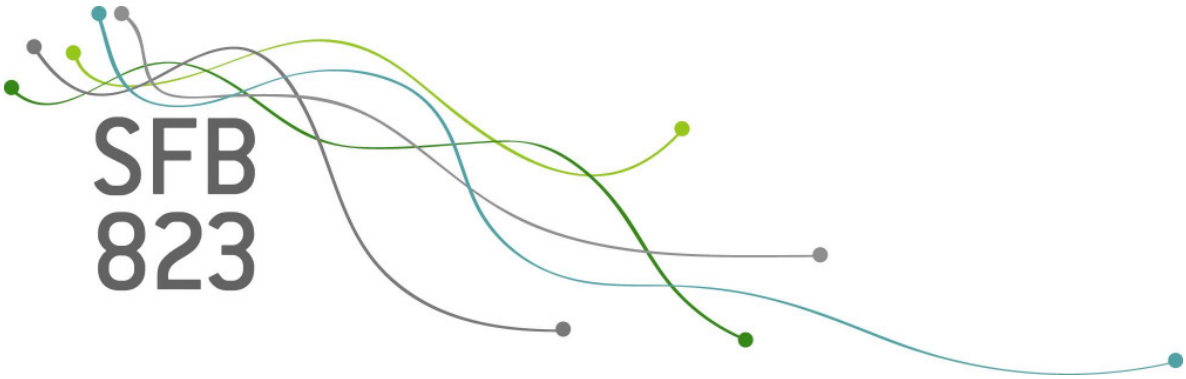

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A COPULA-BASED NONPARAMETRIC MEASURE OF REGRESSION DEPENDENCE

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This paper presents a framework for comparing bivariate distributions according to their degree of regression dependence. We introduce the general concept of a regression dependence order (RDO). In addition, we define a new nonparametric measure of regression dependence and study its properties. Beside being monotone in the new RDOs, the measure takes on its extreme values precisely at independence and almost sure functional dependence, respectively. A consistent nonparametric estimator of the new measure is constructed and its asymptotic properties are investigated. Finally, the finite sample properties of the estimate are studied by means of small simulation study.

1. Introduction and motivation. There is an extensive body of literature on the problem of ordering and measuring the dependence of two random variables. Almost all of the research in this area is concerned with the concept of positive dependence. Orders of positive dependence were considered by many authors, e.g., Lehmann [16], Esary et al. [7] and Schriever [24]; see also Scarsini and Shaked [23] for a detailed survey. Axiomatic approaches to orders and measures of positive dependence were introduced by Kimeldorf and Sampson [14] and Scarsini [22], respectively. The abundance of notions of positive dependence contrasts, however, with the silence concerning regression dependence, with the exception of the work of Dąbrowska [3, 4] and the measure suggested by Hall [12].

This paper presents a new approach to the problem of ordering and measuring regression dependence in the bivariate case. The terms "order" and "ordering" are used in the sense of a preorder, i.e., a reflexive and transitive relation. We drop the requirement of antisymmetry in order to allow for an arbitrary functional form of the regression. For convenience, an order for random variables and the corresponding relations for distributions and distribution functions are used synonymously. Also, we do not strictly dis-

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criminate between distribution functions and distributions; the notation is the same.

Let (X, Y) be a random vector with marginal distribution functions F_X and F_Y, respectively, and joint distribution function $F_{X,Y}$. Since regression dependence is a directional relationship, it is first necessary to specify the direction of interest. Without loss of generality, we study the dependence of Y on X. The fundamental idea behind regression is predictability—the more predictable Y is from X, the more regression dependent they are. It is straightforward to single out the two extreme cases: independence and almost sure functional dependence, when there exists a Borel measurable function g such that $Y = g(X)$ with probability one; see Lancaster [15]. In the former case, X provides no information about Y, whereas in the latter case there is perfect predictability of Y from X.

Apart from the two extreme cases, however, there exists a variety of intermediate ones with a certain degree of regression dependence in a sense yet to be specified. The essence of our approach is the fact that the predictability of Y from X is intrinsically related to the variability of the conditional distributions $F_{Y|X=x}$ of Y given $X = x$. More precisely, the less variable $F_{Y|X=x}$, the more predictable Y from X, and thus the more regression dependent (X, Y). For example, perfect predictability, i.e. almost sure functional dependence of Y on X, is equivalent to the degeneracy of $F_{Y|X=x}$ for almost all x. Unless otherwise stated "almost" is used in the sense of the respective probability measure, which is clear from the context. It follows that, if $(\widetilde{X}, \widetilde{Y})$ is another pair of random variables, then the general idea is to consider (X, Y) less regression dependent than $(\widetilde{X}, \widetilde{Y})$ if $F_{Y|X=x}$ is more variable than $F_{\widetilde{Y}|\widetilde{X}=x}$ for almost all x. Therefore, a bivariate regression dependence order is associated to a univariate variability order, and different variability orders could lead, in general, to different regression orders.

This approach, however, is not applicable unless X and $\widetilde{X}$ have the same distribution. Moreover, it is even necessary that Y and $\widetilde{Y}$ are identically distributed because, otherwise, their different variability will affect the variability of $F_{Y|X}$ and $F_{\widetilde{Y}|\widetilde{X}}$ and, in this way, the degree of regression dependence. For this reason, a comparison of two bivariate random vectors with arbitrary marginals is possible only after their transformation to the same Fréchet class. If the marginals are continuous, it is natural to consider the probability integral transformations $(U, V) = (F_X(X), F_Y(Y))$ and $(\widetilde{U}, \widetilde{V}) = (F_{\widetilde{X}}(\widetilde{X}), F_{\widetilde{Y}}(\widetilde{Y}))$, which have uniform marginal distributions. In this case, we regard (X, Y) less regression dependent than $(\widetilde{X}, \widetilde{Y})$ if $F_{V|U=u}$ is more variable than $F_{\widetilde{V}|\widetilde{U}=u}$ for almost all u.

It should be noted, however, that while lower variability of the conditional

distributions is a necessary condition for defining a regression dependence order, it is not sufficient. As the details will be given later in Section 3, we only mention here that the choice of the variability order cannot be arbitrary, but should take into account the two extremes of regression dependence, namely, independence and almost sure functional dependence. We will show that the most common variability orders lead indeed to regression orders.

In Section 4 we introduce a new nonparametric measure of regression dependence, study its properties and demonstrate its advantages over the correlation ratio. Beside being monotone in the new regression orders, the measure possesses several appealing properties. For instance, it takes on its minimum if and only if X and Y are independent, and its maximum if and only if Y is almost surely (a.s.) a Borel function of X.

Two estimates of the new dependence measure are introduced in Section 5 and their asymptotic properties are investigated. Finally, Section 6 contains a small simulation study which shows that the proposed estimates have a reasonable performance for moderate sample size.

2. Notation and preliminaries. This section introduces the notation and states some technical facts which will be needed in the sequel. Except for the results on univariate variability orders, attention is restricted to the set $\mathfrak{F}$ of all bivariate distribution functions with continuous marginal distribution functions, as well as the set $\mathfrak{X}$ of all bivariate random vectors with distribution functions in $\mathfrak{F}$. For $(X,Y) \in \mathfrak{X}$, $F_{X,Y} \in \mathfrak{F}$ denotes its joint distribution function with marginal distribution functions F_X and F_Y, respectively, while $F_{Y|X=x}$ denotes the conditional distribution function of Y given $X = x$. For the probability integral transformations of $(X,Y) \in \mathfrak{X}$ we shall write

$$U := F_X(X) \text{ and } V := F_Y(Y)\,.$$

Thus, U and V have uniform distributions on the closed unit interval $[0,1]$, which will be denoted by I. The notation $F_{U,V}$ and $F_{V|U=u}$ will be used for joint and conditional distribution of (U,V) and V given $U = u$, respectively. The first result describes the two extreme cases of regression dependence for (X,Y) in terms of (U,V).

PROPOSITION 2.1. *For any $(X,Y) \in \mathfrak{X}$, the following are true:*

(i) X and Y are independent if and only if U and V are independent.
(ii) U and V are independent if and only if $F_{V|U=u} = F_V$ for almost all u.
(iii) Y is a.s. a Borel function of X if and only if V is a.s. a Borel function of U.

(iv) V is a.s. a Borel function of U if and only if $F_{V|U=u}$ is degenerate for almost all u.

PROOF. (i) and (ii) are obvious. As for (iii), since F_X is continuous, $Y = f \circ X$ a.s. implies $Y = f \circ F_X^{-1} \circ F_X \circ X$ a.s., so that $V = g \circ U$ a.s. with the measurable function $g := F_Y \circ f \circ F_X^{-1}$; conversely, if $V = g \circ U$ we set $f := F_Y^{-1} \circ g \circ F_X$. Finally, (iv) follows from the observation that $V = f(U)$ is equivalent to the fact that the graph of f is measurable and has probability one, i.e.,

$$1 = \int_{I^2} \mathbf{1}_{\operatorname{gr} f}(u,v)\, dF_{U,V}(u,v) = \int_I \int_I \mathbf{1}_{\operatorname{gr} f}(u,v)\, dF_{V|U=u}(v)\, dF_U(u).$$

This is equivalent to $F_{V|U=u}$ being degenerate for almost all u. □

Since we work with the probability integral transformations, the concept of copulas is tailored for our approach. Formally, a bivariate copula (or briefly, a copula) is the restriction to I^2 of a bivariate distribution function with uniform marginals on I. In fact, the unique copula $C_{X,Y}$ of $(X,Y) \in \mathfrak{X}$ coincides with $F_{U,V}$ on I^2. In particular, the copula corresponding to independent variables is the product copula $P(u,v) = uv$.

Denote by $\mathfrak{C}$ the set of all copulas, and by $\partial_i C$ the partial derivative of $C \in \mathfrak{C}$ with respect to the i-th variable. The following properties of copulas are easy consequences of the definition; for a proof see, e.g., [18].

PROPOSITION 2.2. *For any $C \in \mathfrak{C}$, the following statements are true:*

(i) C is Lipschitz continuous; more precisely, for all $(u_1,v_1),(u_2,v_2) \in I^2$ we have

$$|C(u_2,v_2) - C(u_1,v_1)| \le |u_2 - u_1| + |v_2 - v_1|.$$

(ii) For each $v \in I$, $\partial_1 C(u,v)$ exists for almost all $u \in I$; similarly, for each $u \in I$, $\partial_2 C(u,v)$ exists for almost all $v \in I$. Moreover, the partial derivatives satisfy

$$0 \le \partial_i C \le 1$$

for $i = 1,2$ wherever they are defined.

REMARK 2.3. (i) Note that the Lipschitz continuity implies that a copula is absolutely continuous in each argument, so that it can be recovered from any of its partial derivatives by integration.

(ii) In fact, we have $0 \leq \partial_i C \leq 1$ for $i = 1, 2$ Lebesgue almost everywhere (a.e.) on I^2 since, as Lipschitz continuous functions, copulas are differentiable Lebesgue a.e. in view of Rademacher's Theorem; see [8]. Moreover, by [8, Thm. 5.8.4], we also have $\partial_i C \in L^p(I^2, \mathbb{R})$ with $p \geq 1$.

There is a relationship between the conditional distribution $F_{V|U=u}$ and the corresponding copula $C_{X,Y}$, which is given by

$$F_{V|U=u}(v) = \partial_1 C_{X,Y}(u, v) \tag{2.1}$$

wherever the partial derivative exists; see [18]. Moreover, we have the following result related to Proposition 2.1.

PROPOSITION 2.4. *For any $(X, Y) \in \mathfrak{X}$, the following are true:*

(i) X and Y are independent if and only if $\partial_1 C_{X,Y}(u, v) = v$ for Lebesgue almost all $(u, v) \in I^2$.

(ii) Y is a.s. a Borel function of X if and only if $\partial_1 C_{X,Y}(u, v) \in \{0, 1\}$ for Lebesgue almost all $(u, v) \in I^2$.

PROOF. The first statement follows from Remark 2.3 (i), while the second is a consequence of [5, Thm. 11.1] and [26, Thm. 4.2]. □

Since our approach to ordering regression dependence employs the variability of the conditional distribution functions, the rest of this section deals with stochastic orders that compare the variability or dispersion of two arbitrary random variables X and Y (or their univariate distributions F_X and F_Y); we refer to [17] and [25] for a detailed study of stochastic orders.

Probably the most common variability order is the convex order. X is smaller than Y in the convex order (denoted as $X \leq_{\text{cx}} Y$) if

$$\mathrm{E}[\phi(X)] \leq \mathrm{E}[\phi(Y)] \tag{2.2}$$

for all convex functions $\phi : \mathbb{R} \to \mathbb{R}$, provided the expectations exist. Depending on the context, i.e., whether working with random variables or distribution functions, we write $X \leq_{\text{cx}} Y$ or $F_X \leq_{\text{cx}} F_Y$. This order reflects the intuitive idea that convex functions take on their (relatively) larger values over regions of the form $(-\infty, a) \cup (b, \infty)$ for $a < b$. Therefore, if (2.2) holds, Y is more variable (or more dispersed) than X. The next result is a direct consequence of (2.2).

PROPOSITION 2.5. *Let X and Y be two random variables. If $X \leq_{cx} Y$, then $E[X] = E[Y]$ and $Var[X] \leq Var[Y]$.*

As can be seen from Proposition 2.5, only random variables with the same expectations can be compared. When X and Y have finite expectations, we can use the convex order to define a location-free variability order. Namely, we call X smaller than Y in the dilation order (denoted as $X \leq_{\mathrm{dil}} Y$) if

$$X - \mathrm{E}[X] \leq_{\mathrm{cx}} Y - \mathrm{E}[Y]. \tag{2.3}$$

COROLLARY 2.6. *Let X and Y be two random variables. If $X \leq_{dil} Y$, then $Var[X] \leq Var[Y]$.*

Another important location-free variability order is the dispersive order. F_X is smaller than F_Y in the dispersive order (denoted as $F_X \leq_{\mathrm{disp}} F_Y$) if

$$F_X^{-1}(b) - F_X^{-1}(a) \leq F_Y^{-1}(b) - F_Y^{-1}(a) \tag{2.4}$$

for all $0 < a \leq b < 1$. As noted in [25], it is conceptually clear that this order compares the variability of F_X and F_Y because it requires the difference between any two quantiles of F_X to be smaller than the corresponding quantiles of F_Y.

The next result shows the relation between the orders $\leq_{\mathrm{disp}}$ and $\leq_{\mathrm{dil}}$; compare [25, Thm. 3.B.16].

PROPOSITION 2.7. *Let X and Y be two random variables with finite expectations. Then $X \leq_{disp} Y$ implies $X \leq_{dil} Y$.*

3. Regression dependence orders. The fundamental idea to introduce an order of regression dependence on $\mathfrak{X}$ (respectively $\mathfrak{F}$) is to compare the variability of the conditional distributions, since low and high dispersion is tantamount to high and low predictability, respectively. However, as discussed in the introduction, a comparison of two elements of $\mathfrak{X}$ with arbitrary marginals is possible only after their transformation to the same Fréchet class which can be accomplished using the probability integral transformations. Essentially, a random vector $(X, Y) \in \mathfrak{X}$ is less regression dependent than another random vector $(\widetilde{X}, \widetilde{Y}) \in \mathfrak{X}$ if $F_{\widetilde{V}|\widetilde{U}=u}$ is less variable (in some univariate variability order) than $F_{V|U=u}$ for almost all u. More precisely, we adopt the following definition.

DEFINITION 3.1. *A relation $\preccurlyeq$ on $\mathfrak{X}$ (or $\mathfrak{F}$) is a regression dependence order (RDO) if it is reflexive and transitive, and satisfies the following:*

(O1) $(X, Y) \preccurlyeq (\widetilde{X}, \widetilde{Y})$ implies $F_{\widetilde{V}|\widetilde{U}=u} \leq_\bullet F_{V|U=u}$ for almost all $u \in I$, where $\leq_\bullet$ is a univariate variability order;

(O2) If Y is a.s. a Borel function of X, and if $(X,Y) \preccurlyeq (\widetilde{X},\widetilde{Y})$, then $\widetilde{Y}$ is a.s. a Borel function of $\widetilde{X}$;

(O3) If X and Y are independent, and if $(\widetilde{X},\widetilde{Y}) \preccurlyeq (X,Y)$, then $\widetilde{X}$ and $\widetilde{Y}$ are independent.

Property $(O1)$ indicates that an RDO is always associated to a given variability order. Therefore, a relation $\preccurlyeq$ satisfying $(O1)$ with respect to the univariate variability order $\leq_\bullet$ will be denoted by $\preccurlyeq_\bullet$.

Conditions $(O2)$ and $(O3)$ deal with the two extreme cases. Since almost sure functional dependence is equivalent to perfect predictability of Y from X, the corresponding distribution must have the greatest regression dependence possible. Consequently, any distribution which is more dependent must also correspond to almost sure functional dependence; hence $(O2)$. Similarly, the least dependent situation is given when X and Y are independent. Hence, any less dependent distribution must be again the distribution of independent random variables, which is expressed in $(O3)$.

In view of condition $(O1)$, probably the easiest way to construct an RDO is to choose some variability order $\leq_\bullet$, define $(X,Y) \preccurlyeq (\widetilde{X},\widetilde{Y})$ if and only if $F_{\widetilde{V}|\widetilde{U}=u} \leq_\bullet F_{V|U=u}$ for almost all $u \in I$, and check whether conditions $(O2)$ and $(O3)$ are satisfied. In fact, since no distribution is less dispersed than a degenerate one, $(O2)$ should always be satisfied in view of Proposition 2.1, and it remains to prove $(O3)$.

It is important to note that an RDO corresponding to a variability order which is not location-free (e.g., the convex order $\leq_{\mathrm{cx}}$) is unnecessarily restrictive, for then only distributions with the same regression function can be compared. However, since we want to compare the strength of regression dependence with respect to possibly different regression functions, we will consider location-free orders only. Amongst them, the dilation order $\leq_{\mathrm{dil}}$ and the dispersive order $\leq_{\mathrm{disp}}$ are the most important and common ones. The next result states that the corresponding relations $\preccurlyeq_{\mathrm{dil}}$ and $\preccurlyeq_{\mathrm{disp}}$ are indeed RDOs.

THEOREM 3.2. *The relations $\preccurlyeq_{dil}$ and $\preccurlyeq_{disp}$ are RDOs.*

PROOF. In view of Proposition 2.7 we need only prove $(O2)$ and $(O3)$ for the relation $\preccurlyeq_{\mathrm{dil}}$. It is clear from Corollary 2.6 that $\preccurlyeq_{\mathrm{dil}}$ satisfies $(O2)$. In order to prove $(O3)$ we may, in view of Proposition 2.1, restrict to considering U and V instead of X and Y. Assuming that $(\widetilde{U},\widetilde{V}) \preccurlyeq_{\mathrm{dil}} (U,V)$ with independent U and V, we conclude from Corollary 2.6 that

$$\mathrm{Var}[\widetilde{V}|\widetilde{U}=u] \geq \frac{1}{12} \tag{3.1}$$

for almost all u. By the law of total variance, we obtain equality in (3.1), as well as

$$\mathrm{E}[\widetilde{V}|\widetilde{U}=u]=\mathrm{E}[\widetilde{V}]=\frac{1}{2} \tag{3.2}$$

for almost all u. From (3.2) and (3.1) it follows that, for almost all u, $F_{V|U=u} \leq_{\mathrm{cx}} F_{\widetilde{V}|\widetilde{U}=u}$ with equal variances. But then both distributions are the same; see [25, Thm. 3.A.42]. This proves $(O3)$, and hence the theorem. □

4. Measures of regression dependence. We now turn to the subject of how to measure the degree of regression dependence in the set $\mathfrak{X}$ (or $\mathfrak{F}$). It is clear that without specifying an RDO any discussion of measures of regression dependence is problematic. We adopt the following definition.

Definition 4.1. *Let $\preccurlyeq$ be an arbitrary RDO. A function $\mu : \mathfrak{X} \to [0,1]$ is a measure of regression dependence (MRD) with respect to $\preccurlyeq$ if it satisfies the following conditions:*

(M1) $(X,Y) \preccurlyeq (\widetilde{X},\widetilde{Y})$ *implies* $\mu(X,Y) \leq \mu(\widetilde{X},\widetilde{Y})$*;*
(M2) $\mu(X,Y)=1$ *if and only if* Y *is a.s. a Borel function of* X*;*
(M3) $\mu(X,Y)=0$ *if and only if* X *and* Y *are independent.*

Remark 4.2. Alternatively, μ can also be defined as a functional on $\mathfrak{F}$, and we sometimes write $\mu(F_{X,Y})$ instead of $\mu(X,Y)$.

Condition $(M1)$ is the usual monotonicity property required by any measure of dependence. $(M2)$ and $(M3)$ concern the two extreme cases of regression dependence. We point out how strong both conditions are—in fact, a measure of dependence satisfying $(M2)$ and $(M3)$ has not yet been proposed in the literature. For instance, $(M2)$ is much stronger than Rényi's corresponding postulate in [21], according to which a measure of dependence should take on its maximal value 1 if one of X and Y is a.s. a function of the other. What is more, Rényi mentioned that it is natural to pose an "only if" requirement, but since the condition was rather restrictive, it was better to leave it out. With respect to $(M3)$, we point out that the well-known correlation ratio is not a MRD in the sense of Definition 4.1 because it attains its minimum at 0 not only when X and Y are independent; examples are presented later in this section.

We now turn to the construction of a nonparametric MRD. The following is the main result in this section.

THEOREM 4.3. *The function $r : \mathfrak{X} \to [0,1]$ defined by*

$$r(X,Y) = 6\int_0^1 \int_0^1 F_{V|U=u}(v)^2 \, dv \, du - 2 \tag{4.1}$$

is a MRD concurring with both $\preccurlyeq_{dil}$ and $\preccurlyeq_{disp}$.

REMARK 4.4. Note that in view of (2.1), we have

$$r(X,Y) = 6\|\partial_1 C_{X,Y}\|_2^2 - 2 \tag{4.2}$$

where $\|\cdot\|_2$ denotes the L^2-norm on I^2. By Remark 2.3 (ii), this shows that r is indeed well defined. Moreover, r can also be viewed as a functional on the set of copulas $\mathfrak{C}$, and we write $r(C_{X,Y}) = r(X,Y)$.

In order to prove Theorem 4.3 we make use of the following result.

LEMMA 4.5. *For any $C_{X,Y} \in \mathfrak{C}$, we have $\|\partial_1 C_{X,Y}\|_2^2 \in [1/3, 1/2]$. Moreover, the following assertions hold:*

(i) $\|\partial_1 C_{X,Y}\|_2^2 = 1/3$ if and only if X and Y are independent.
(ii) $\|\partial_1 C_{X,Y}\|_2^2 = 1/2$ if and only if Y is a.s. a Borel function of X.

PROOF. *(i)* Consider the inequality

$$0 \le \int_0^1 \int_0^1 (\partial_1 C_{X,Y}(u,v) - v)^2 \, du \, dv = \int_0^1 \int_0^1 (\partial_1 C_{X,Y}(u,v))^2 \, du \, dv - \frac{1}{3}.$$

Hence, $\|\partial_1 C_{X,Y}\|_2^2 \ge 1/3$ with equality if and only if $\partial_1 C_{X,Y}(u,v) = v$ Lebesgue a.e. on I^2, which by Proposition 2.4 (i) is equivalent to the independence of X and Y.

(ii) By Theorem 2.2 (ii) we have $0 \le \partial_1 C_{X,Y} \le 1$ and thus $(\partial_1 C_{X,Y})^2 \le \partial_1 C_{X,Y}$, with equality if and only if $\partial_1 C_{X,Y} \in \{0,1\}$. Consequently,

$$\|\partial_1 C_{X,Y}\|_2^2 \le \int_0^1 \int_0^1 \partial_1 C_{X,Y}(u,v) \, du \, dv = \frac{1}{2}$$

with equality if and only if $\partial_1 C_{X,Y} \in \{0,1\}$ Lebesgue a.e. in I^2, which by Proposition 2.4 (ii) is equivalent to Y being a.s. a Borel function of X. □

We will also make use of the following representation formula for univariate distribution functions whose support is contained in I. The proof uses integration by parts for Lebesgue-Stieltjes integrals (see, e.g., [13, Thm. 21.67]) and is omitted.

LEMMA 4.6. *Let F be a univariate distribution function with support in I. Then*

$$2\int_0^1\int_0^p F^{-1}(t)\,dt\,dp - \int_0^1 F^{-1}(t)\,dt = \int_0^1 F(v)^2\,dv - \int_0^1 F(v)\,dv.$$

We now turn to the proof of the theorem.

PROOF OF THEOREM 4.3. The property $0 \le r(X,Y) \le 1$, as well as the conditions $(M2)$ and $(M3)$, are immediately implied by Lemma 4.5.

It remains to show the monotonicity condition $(M1)$; in view of Proposition 2.7, it suffices to prove it for the RDO $\preccurlyeq_{\mathrm{dil}}$. Ramos and Sordo showed in [20, Thm. 2.1] that two univariate distribution functions F and G with finite expectations satisfy $F \le_{\mathrm{dil}} G$ if and only if, for all $v \in [0,1]$,

$$\int_0^v F^{-1}(t)\,dt - v\int_0^1 F^{-1}(t)\,dt \ge \int_0^v G^{-1}(t)\,dt - v\int_0^1 G^{-1}(t)\,dt\,. \tag{4.3}$$

Now assume that $(X,Y) \preccurlyeq_{\mathrm{dil}} (\widetilde{X},\widetilde{Y})$ so that $F_{\widetilde{V}|\widetilde{U}=u} \le_{\mathrm{dil}} F_{V|U=u}$ for almost all $u \in I$. Then, integrating (4.3) over v we obtain

$$\int_0^1\int_0^v F^{-1}_{\widetilde{V}|\widetilde{U}=u}(t)\,dt\,dv - \frac{1}{2}\int_0^1 F^{-1}_{\widetilde{V}|\widetilde{U}=u}(t)\,dt \ge \int_0^1\int_0^v F^{-1}_{V|U=u}(t)\,dt\,dv - \frac{1}{2}\int_0^1 F^{-1}_{V|U=u}(t)\,dt$$

for almost all $u \in I$. Applying Lemma 4.6 we find that, for almost all u,

$$\int_0^1 F_{\widetilde{V}|\widetilde{U}=u}(v)^2\,dv - \int_0^1 F_{\widetilde{V}|\widetilde{U}=u}(v)\,dv \ge \int_0^1 F_{V|U=u}(v)^2 dv - \int_0^1 F_{V|U=u}(v)\,dv\,.$$

Integrating this over $u \in I$, substituting $\partial_1 C_{X,Y}(u,v)$ for $F_{V|U=u}(v)$ by (2.1), and using $\int_0^1\int_0^1 \partial_1 C_{X,Y}(u,v)\,dv\,du = 1/2$ for all $C_{X,Y} \in \mathfrak{C}$, we obtain

$$\|\partial_1 C_{\widetilde{X},\widetilde{Y}}\|_2^2 = \int_0^1\int_0^1 (\partial_1 C_{\widetilde{X},\widetilde{Y}}(u,v))^2\,dv\,du \ge \int_0^1\int_0^1 (\partial_1 C_{X,Y}(u,v))^2\,dv\,du = \|\partial_1 C_{X,Y}\|_2^2.$$

Since, by Remark 4.4, $r(X,Y) = 6\|\partial_1 C_{X,Y}\|_2^2 - 2$, this proves $(M1)$ and hence the theorem. □

PROPOSITION 4.7. *If $f, g : \mathbb{R} \to \mathbb{R}$ are strictly monotone functions then*

$$r(f(X), g(Y)) = r(X, Y)\,.$$

PROOF. We distinguish four different cases. If f and g are both increasing, it is well known [18, Theorem 2.4.3] that

$$C_{f(X),g(Y)} = C_{X,Y}\,,$$

which immediately implies $r(f(X), g(Y)) = r(X, Y)$. If f is increasing and g is decreasing, then

$$C_{f(X),g(Y)}(u, v) = u - C_{X,Y}(u, 1 - v);$$

see [18, Theorem 2.4.4]. Therefore, we conclude $\|\partial_1 C_{f(X),g(Y)}\|_2^2 = \|\partial_1 C_{X,Y}\|_2^2$, which again implies $r(f(X), g(Y)) = r(X, Y)$. If f is decreasing and g is increasing, the result follows from interchanging f and g in the previous case. The final case when f and g are both decreasing can be shown similarly. □

We now turn attention to another quantity that might seem a natural choice for an MRD, namely the correlation ratio of the probability integral transformations. Define the functional $\widetilde{\eta} : \mathfrak{X} \to \mathbb{R}$ by

$$\widetilde{\eta}(X, Y)^2 := \eta(U, V)^2 = \frac{\mathrm{Var}[\mathrm{E}[V|U]]}{\mathrm{Var}[V]} = 1 - \frac{\mathrm{E}[\mathrm{Var}[V|U]]}{\mathrm{Var}[V]}\,. \tag{4.4}$$

Since $\mathrm{Var}[V] = 1/12$, it follows that

$$\widetilde{\eta}(X, Y)^2 = 12\mathrm{Var}[\mathrm{E}[V|U]]\,.$$

In fact, the ordering of regression dependence suggested in [3, Sec. 3.1] is an ordering by correlation ratios and therefore is not consistent with our approach to RDOs. Moreover, neither the correlation ratio of Y on X nor the related measure $\widetilde{\eta}(X, Y)^2$ are MRDs in the sense of Definition 4.1, because $(M3)$ will not be satisfied. Indeed, it follows from Propositions 2.7 and 2.5 that $\widetilde{\eta}$ is monotone with respect to both $\preccurlyeq_{\mathrm{disp}}$ and $\preccurlyeq_{\mathrm{dil}}$; in addition, $\widetilde{\eta}(X, Y) = 1$ if and only if Y is a.s. a Borel function of X. However, $\widetilde{\eta}$ does not satisfy condition $(M3)$ because there are random variables X and Y with $\widetilde{\eta}(X, Y) = 0$, which are not independent; we give two such examples.

EXAMPLE 4.8. Consider X and Y whose probability integral transformations U and V have the singular distribution with the support depicted in Figure 1(a). The support is the union of the main and secondary diagonal in I^2, so that probability mass $1/2$ is uniformly distributed on each line

(a) Support of the distribution of (U, V) in Example 4.8

(b) Support of the distribution of (U, V) in Example 4.9

FIG 1. *Examples of $\widetilde{\eta}(X, Y) = 0$ where X and Y are not independent*

segment. For every $u \in I$, the resulting conditional distribution $F_{V|U=u}$ is a two-point distribution at $v = u$ and $v = 1 - u$ and, thus, $E[V|U = u] = 1/2$. Consequently, the conditional expectation $E[V|U]$ is degenerate and its variance $\mathrm{Var}[\mathrm{E}[V|U]]$ vanishes, which means that $\eta(U, V) = \widetilde{\eta}(X, Y) = 0$. However, U and V and, thus, X and Y are not independent.

EXAMPLE 4.9. Another situation where $\widetilde{\eta}(X, Y) = 0$ but X and Y are not independent is given when $F_{X,Y}$ is the circular uniform distribution. It is well known that in this case the ordinary correlation ratio $\eta(X, Y)$ vanishes. The same is true for the related measure $\widetilde{\eta}(X, Y)$ since in this case $F_{U,V}$ is a degenerate distribution whose support is given in Figure 1(b); see [18, Sec. 3.1.2]. The arguments are analogous to those in the previous example.

5. Nonparametric estimation of r. In this section we present a sample version of the MRD defined in (4.2). As pointed out in Remark 4.4, r is a function of the copula $C_{X,Y}$ alone. $C_{X,Y}$ can be consistently estimated by the empirical copula; see Deheuvels [6] and Fermanian et al. [10]. However, the empirical copula is locally constant and, thus, the estimation of r is more involved since it requires the estimation of the copula's partial derivative. The need for differentiability calls for a smooth (differentiable) estimation of the copula, e.g., with a kernel-based technique.

For this purpose let $(X_1, Y_1), \ldots (X_n, Y_n)$ denote independent identically distributed random variables with distribution function F and copula C, let K denote a symmetric kernel with compact support, say $[-1, 1]$, with

corresponding cumulative distribution function

$$\overline{K}(x) = \int_{-\infty}^{x} K(t)\ dt.$$

As an estimate for the partial derivative of the copula $\tau(u,v) = \frac{\partial}{\partial u}\ C(u,v)$ we use

$$\hat{\tau}_n(u,v) = \frac{1}{nh_1} \sum_{i=1}^{n} \omega\Big(\frac{u - \hat{F}_{n1}(X_i)}{h_1}, \frac{v - \hat{F}_{n2}(Y_i)}{h_2}\Big), \tag{5.1}$$

where $\hat{F}_{n1}$ and $\hat{F}_{n2}$ denote the empirical distribution functions of $X_1, \ldots, X_n$ and $Y_1, \ldots, Y_n$, respectively, h_1, h_2 denote bandwidths converging to 0 with increasing sample size and $\omega(x,y) = K(x)\overline{K}(y)$. Note that $\hat{\tau}_n$ is an integrated version of the estimate for the copula density considered in Fermanian [9]. Intuitively, we have for large sample size

$$\begin{aligned} E[\hat{\tau}_n(u,v)] &\approx \frac{1}{h_1} \int \omega\left(\frac{u - F_X(x)}{h_1}, \frac{v - F_Y(y)}{h_2}\right) dF(x,y) \\ &= \frac{1}{h_1} \int_0^1 \int_0^1 \omega\left(\frac{u-s}{h_1}, \frac{v-t}{h_2}\right) c(s,t)\ dsdt \\ &= \int_0^1 \overline{K}\left(\frac{v-t}{h_2}\right) c(u,t)\ dt \cdot (1 + o(1)) \\ &= \int_0^v c(u,t)\ dt \cdot (1 + o(1)) = \frac{\partial}{\partial u}\ C(u,v)(1 + o(1)), \end{aligned}$$

where F_X, F_Y denote the marginal distributions of (X_1, Y_1) and $c(s,t)$ is the copula density. The following result makes these heuristic arguments more precise and gives a corresponding statement for the integrated version of $\hat{\tau}_n(u,v)$

$$\hat{\tau}_n^2 = \int_0^1 \int_0^1 \hat{\tau}_n^2(u,v)\ dudv, \tag{5.2}$$

which will serve as an estimate for the quantity

$$\tau^2 = \int_0^1 \int_0^1 \parallel \partial_1\ C(u,v) \parallel_2^2\ \ dudv.$$

The estimate of the measure $\tau = r(X,Y)$ defined in (4.2) is finally given by

$$\hat{r}_n = 6\hat{\tau}_n^2 - 2. \tag{5.3}$$

The next results show that $\hat{\tau}_n^2$ and $\hat{r}_n$ are asymptotically normal distributed.

THEOREM 5.1. *Assume that the copula $C(u,v)$ is three and two times continuously differentiable with respect to the variable u and v, respectively. If the kernel K is symmetric, two times continuously differentiable with compact support and the bandwidths h_1 and h_2 satisfy*

$$h_j \longrightarrow 0 \qquad (j=1,2) \tag{5.4}$$

$$nh_1^3 \longrightarrow \infty\ ; \qquad nh_1h_2 \longrightarrow \infty\ ; \qquad nh_1^4 \longrightarrow 0, \tag{5.5}$$

then

$$\sqrt{n}\ (\hat{r}_n - r) \xrightarrow{\mathcal{D}} \mathcal{N}(0, 144\sigma^2),$$

where

$$\sigma^2 = \int_0^1\int_0^1\int_0^1 \tau(s, v\wedge w)\tau(s,v)\tau(s,w)\ dsdvdw - \left(\int_0^1\int_0^1 \tau^2(u,v)\ dudv\right)^2.$$

PROOF. The assertion follows from (5.3) and the weak convergence

$$\sqrt{n}\ (\hat{\tau}_n^2 - \tau^2) \xrightarrow{\mathcal{D}} \mathcal{N}(0, 4\sigma^2). \tag{5.6}$$

Recalling the definition of $\hat{\tau}_n(u,v)$ and $\hat{\tau}_n^2$ in (5.1) and (5.2) and using the notation

$$(\omega_{h_1,h_2} * c)(u,v) = \frac{1}{h_1}\int_0^1\int_0^1 \omega\Big(\frac{u-u_1}{h_1}, \frac{v-v_1}{h_2}\Big)c(u_1,v_1)\ du_1dv_1$$

we obtain the decomposition

$$\hat{\tau}_n^2 = B_{1n} + 2B_{2n} + B_{3n}, \tag{5.7}$$

where

$$\begin{aligned}
B_{1n} &= \int_0^1\int_0^1 (\hat{\tau}_n - \omega_{h_1,h_2} * c)^2(u,v)\ dudv,\\
B_{2n} &= \int_0^1\int_0^1 (\hat{\tau}_n - \omega_{h_1,h_2} * c)(u,v)\cdot(\omega_{h_1,h_2} * c)(u,v)\ dudv,\\
B_{3n} &= \int_0^1\int_0^1 (\omega_{h_1,h_2} * c)^2(u,v)\ dudv.
\end{aligned}$$

Similar arguments as given in Fermanian [9] show that

$$B_{1n} = O_p\left(\frac{1}{n\sqrt{h_1}}\right) = o_p\left(\frac{1}{\sqrt{n}}\right), \tag{5.8}$$

while standard arguments (using the differentiability of the copula) yield

$$B_{3n} = \tau^2 + O(h_1^2), \tag{5.9}$$

$$B_{2n} = \hat{B}_{2n}(1 + o_p(1)), \tag{5.10}$$

where the quantity $\hat{B}_{2n}$ is defined by

$$\hat{B}_{2n} = \int_0^1 \int_0^1 (\hat{\tau}_n - \omega_{h_1,h_2} * c)(u,v) \cdot \tau(u,v)\ dudv.$$

We will show at the end of this proof that

$$\hat{B}_{2n} - \tilde{B}_{2n} = o_P\Big(\frac{1}{\sqrt{n}}\Big), \tag{5.11}$$

where the statistic $\tilde{B}_{2n}$ is obtained from $\hat{B}_{2n}$ by replacing the empirical distribution function $\hat{F}_{n1}$ and $\hat{F}_{n2}$ by their theoretical counterparts F_X and F_Y, respectively, that is

$$\tilde{B}_{2n} = \int_0^1 \int_0^1 (\tilde{\tau}_n - \omega_{h_1,h_2} * c)(u,v) \cdot \tau(u,v)\ dudv$$

with

$$\tilde{\tau}_n(u,v) = \frac{1}{nh_1} \sum_{i=1}^{n} \omega\left(\frac{u - F_X(X_i)}{h_1}, \frac{v - F_Y(Y_i)}{h_2}\right). \tag{5.12}$$

Obviously, $\tilde{B}_{2n}$ is of order $O_p(\frac{1}{\sqrt{n}})$ and observing (5.7), (5.8) and (5.9) - (5.11) now yields

$$\sqrt{n}(\hat{\tau}_n^2 - \tau^2) = 2\sqrt{n}\tilde{B}_{2n} + o_P(1). \tag{5.13}$$

The assertion can now be proved by showing the asymptotic normality of

$$\sqrt{n}\ \tilde{B}_{2n} = \frac{1}{\sqrt{n}} \sum_{i=1}^{n} \big(X_{ni} - E[X_{ni}]\big)$$

with

$$X_{ni} = \frac{1}{h_1} \int_0^1 \int_0^1 \omega\Big(\frac{u - F_X(X_i)}{h_1}, \frac{v - F_Y(X_i)}{h_2}\Big)\tau(u,v)\ dudv \tag{5.14}$$

$(i = 1, \dots, n)$. The expectation of X_{ni} is given by $E[X_{ni}] = \tau^2 + O(h_1^2)$ while the second moment is obtained by a tedious but straightforward calculation, i.e.

$$\begin{aligned} E[X_{n1}^2] &= \frac{1}{h_1^2} \int_{[0,1]^4} \int_{[0,1]^2} \omega\Big(\frac{u-s}{h_1}, \frac{v-t}{h_2}\Big) \omega\Big(\frac{\tilde{u}-s}{h_1}, \frac{\tilde{v}-t}{h_2}\Big) \\ &\qquad \times \tau(u,v)\tau(\tilde{v},\tilde{u}) c(s,t)\ du d\tilde{u} dv d\tilde{v}\ ds dt \\ &= \int_{[0,1]^3} \tau(s, v \wedge \tilde{v}) \tau(s,v) \tau(s,\tilde{v})\ ds dv d\tilde{v}\ (1 + o(1)). \end{aligned}$$

The asymptotic normality (5.6) now follows from Ljapunoff's Theorem, that is $2\sqrt{n}\tilde{B}_{2n} \xrightarrow{\mathcal{D}} \mathcal{N}(0, 4\sigma^2)$, where

$$\sigma^2 = \lim_{n\to\infty} Var(\sqrt{n}\tilde{B}_{2n}) = \lim_{n\to\infty} Var(X_{n1}) = \lim_{n\to\infty} E[X_{n1}^2] - \tau^2.$$

Proof of the estimate (5.11). We use similar arguments as in Fermanian [9] and obtain

$$\hat{B}_{2n} - \tilde{B}_{2n} = (C_{1n} + C_{2n})\ (1 + o_P(1)), \tag{5.15}$$

where the random variables C_{1n} and C_{2n} are given by

$$C_{in} = \int_0^1 \int_0^1 C_{in}(u,v)\tau(u,v)\ du dv, \qquad i = 1, 2 \tag{5.16}$$

and

$$\begin{aligned} C_{1n}(u,v) &= \frac{1}{nh_1^2} \sum_{i=1}^n K'\Big(\frac{u - F_X(X_i)}{h_1}\Big) \overline{K}\Big(\frac{v - F_Y(Y_i)}{h_2}\Big) \\ &\qquad \times (\hat{F}_{n1}(X_i) - F_X(X_i)), \end{aligned} \tag{5.17}$$

$$\begin{aligned} C_{2n}(u,v) &= \frac{1}{nh_1h_2} \sum_{i=1}^n K\Big(\frac{u - F_X(X_i)}{h_1}\Big) K\Big(\frac{v - F_Y(Y_i)}{h_2}\Big) \\ &\qquad \times (\hat{F}_{n2}(Y_i) - F_Y(Y_i)). \end{aligned} \tag{5.18}$$

A standard calculation shows that

$$\begin{aligned} E[C_{1n}] &= \int_0^1 \int_0^1 E[C_{1n}(u,v)]\tau(u,v)\ du dv \\ &= \frac{1}{nh_1^2} \int_0^1 \int_0^1 E\Big[(1 - F_X(X_1)) K'\Big(\frac{u - F_X(X_1)}{h_1}\Big) \\ &\qquad \times \overline{K}\Big(\frac{v - F_Y(Y_1)}{h_2}\Big)\Big] \tau(u,v)\ du dv \\ &= O\Big(\frac{1}{nh_1}\Big). \end{aligned} \tag{5.19}$$

The calculation of the second moment

$$(5.20)\quad E[C_{1n}^2] \;=\; \int_{[0,1]^4} E[C_{1n}(u,v)C_{1n}(\tilde{u},\tilde{v})]\tau(u,v)\tau(\tilde{u},\tilde{v})\; dudvd\tilde{u}d\tilde{v}$$

is more complicated. For the integrand in this expression we have

$$\begin{aligned}
E[C_{1n}(u,v)C_{1n}(\tilde{u},\tilde{v})] &= \frac{1}{n^2h_1^4}\sum_{i,i'=1}^{n} E\Big[K'\Big(\frac{u-F_X(X_i)}{h_1}\Big)K'\Big(\frac{\tilde{u}-F_X(X_{i'})}{h_1}\Big)\\
&\quad\times\overline{K}\Big(\frac{v-F_Y(Y_i)}{h_2}\Big)\overline{K}\Big(\frac{\tilde{v}-F_Y(Y_{i'})}{h_2}\Big)\\
&\quad\times(\hat{F}_{n1}(X_i)-F_X(X_i))(\hat{F}_{n1}(X_{i'})-F_X(X_{i'}))\Big]\\
&= \frac{1}{n^4h_1^4}\sum_{i,i'=1}^{n}\sum_{k,k'=1}^{n} E\Big[K'\Big(\frac{u-F_X(X_i)}{h_1}\Big)K'\Big(\frac{\tilde{u}-F_X(X_{i'})}{h_1}\Big)\\
&\quad\times\overline{K}\Big(\frac{v-F_Y(Y_i)}{h_2}\Big)\overline{K}\Big(\frac{\tilde{v}-F_Y(Y_{i'})}{h_2}\Big)\\
&\quad\times(I\{X_k\le X_i\}-F_X(X_i))(I\{X_{k'}\le X_{i'}\}-F_X(X_{i'})\Big]\\
&= E[C_{1n}(u,v)]\;E[C_{1n}(\tilde{u},\tilde{v})]+O\Big(\frac{1}{n^2h_1^3}\Big),
\end{aligned}$$

uniformly with respect to $(u,v),(\tilde{u},\tilde{v})\in[0,1]^2$, where the last estimate follows by a careful inspection of the common indices in the tupel (i,i',k,k'). Observing (5.19) and (5.20) this implies $\mathrm{Var}(C_{1n})=O(\frac{1}{n^2h_1^3})$, which yields

$$C_{1n}=O_p\Big(\frac{1}{nh_1^{3/2}}\Big)=o_p\Big(\frac{1}{\sqrt{n}}\Big)$$

by assumption (5.5). The corresponding estimate for the term C_{2n} in (5.15) can be shown by similar arguments, that is

$$C_{2n}=O_p(\frac{1}{n\sqrt{h_1h_2}}),$$

which proves assertion (5.11) and completes the proof of Theorem 5.1. □

It is worthwhile to mention that in any implementation the integral in (5.2) is usually calculated by a numerical integration, that is

$$(5.21)\qquad \hat{\tau}^2_{appr}=\frac{1}{g^2}\sum_{i=1}^{g}\sum_{j=1}^{g}\hat{\tau}^2_n(u_i,v_i)$$

where $\{u_i, v_j\}_{i,j=1}^g$ defines an appropriate grid. If the number of points used in the grid is fixed, then $\hat{\tau}^2_{appr}$ is a consistent estimate of

$$\tau^2_{appr} = \frac{1}{g^2} \sum_{i=1}^{g} \sum_{j=1}^{g} \tau^2(u_i, v_i).$$

The following result shows that the estimate $\hat{r}_{appr} = 6\hat{\tau}^2_{appr} - 2$ converges with a different rate to the quantity $r_{appr} = 6\tau^2_{appr} - 2$. It can be proved by similar arguments as presented in the proof of Theorem 5.1, which are omitted for the sake of brevity.

THEOREM 5.2. *If the assumptions of Theorem 5.1 are satisfied, then*

$$\sqrt{nh_1}(\hat{r}_{appr} - r_{appr}) \xrightarrow{\mathcal{D}} \mathcal{N}(0, 144\sigma^2_{appr})$$

where the asymptotic variance is given by

$$\sigma^2_{appr} = \frac{4}{g^4} \int_{-1}^{1} K^2(x)dx \sum_{i,j,k=1}^{g} \tau(u_i, v_j)\tau(u_i, v_k)\tau(u_i, v_j \wedge v_k).$$

REMARK 5.3. Theorem 5.1 and 5.2 can be generalized to dependent data under suitable mixing properties of the data generating process [11, Assumptions 3 and 4]. The details are omitted for the sake of brevity.

6. Finite sample properties. In this section we present a small simulation study in order to study the finite sample properties of the proposed estimate. We begin with the study of the mean squared error of the estimate when the underlying copula is the Clayton copula, that is

$$C(u, v) = (u^{-\theta} + v^{-\theta} - 1)^{-\theta}; \quad \theta > 0 \tag{6.1}$$

In order to address the problem of boundary effects in the statistic $\hat{\tau}_n$ we have adapted the estimate investigated recently in Chen and Huang [1] and Omelka et al. [19] to our problem. To be precise we have used the statistic

$$\hat{\tau}^{(LLS)}_n(u, v) = \frac{1}{b(u)h_1 n} \sum_{i=1}^{n} K_{u,h_1}\Big(\frac{u - \hat{F}_{m1}(X_i)}{b(u)h_1}\Big)\overline{K}_{v,h_2}\Big(\frac{v - \hat{F}_{n2}(Y_i)}{b(v)h_2}\Big),$$

as an estimate of $\tau(u, v) = \frac{\partial}{\partial u}C(u, v)$ where $b(w) = \min\{\sqrt{w}, \sqrt{1-w}\}$ and the kernel K_{u,h_1} is defined by

$$K_{u,h_1}(x) = \frac{K(x)\{a_2(u, h_1) - a_1(u, h_1)x\}}{a_0(u, h_1)a_2(u, h_1) - a^2_1(u, h_1)} \; I\left\{\frac{u-1}{h_1} < x < \frac{u}{h_1}\right\}$$

with

$$a_\ell(u,h_1)=\int_{(u-1)/h_1}^{u/h_1} t^\ell K(t)dt; \qquad \ell=0,1,2.$$

Note that $\hat\tau_n^{(LLS)}$ is a local linear estimate, where the bandwidth function "shrinks" the value of the bandwidth close to zero at the corners of the unit square.

The estimates $\hat\tau_n^2$ and $\hat\tau_{appr}^2$ are constructed by (5.2) and (5.21), respectively, replacing $\hat\tau_n$ by $\hat\tau_n^{(LLS)}$ and similar arguments as in Chen and Huang [1] and Omelka et al. [19] show that Theorems 5.1 and 5.2 remain valid.

In Table 6 we present the simulated mean squared error of the estimate for the sample sizes 50, 100 and 200. These results are based on 25.000 simulation runs. The bandwidth is chosen as $h=n^{-3/10}$ and the integral in the definition of the estimate is calculated over a grid of 49×49 points. The random variables distributed according to the Clayton copula are generated by the method presented in Cook and Johnson [2]. We observe that in all cases the measure r is estimated with a reasonable precision. It is worthwhile to mention that the estimate is less accurate if $\tau=0$.

In the second part of our numerical study we investigate the approximation by the normal distribution for moderate sample sizes. In order to obtain a good approximation by the limit distribution it is important to have a precise estimate of the limiting variance. For this purpose we propose an estimate which is motivated by a careful inspection of the proof of Theorem 5.1. To be precise, note that by (5.13) the statistic $\sqrt{n}(\hat\tau_n^2-\tau^2)$ is asymptotically equivalent to a sum of iid random variables defined by (5.14), in particular

$$Var(\sqrt{n}\hat\tau_n)\approx 4Var(\sqrt{n}\tilde B_{2n})=4Var(X_{ni}),$$

where X_{ni} is defined in (5.14). Therefore we use the empirical variance of the random variables

$$V_{ni}=\frac{1}{n_1}\int_0^1\int_0^1 \omega\left(\frac{u-\hat F_{n1}(X_i)}{h_1},\frac{v-\hat F_{n2}(Y_i)}{n_2}\right)\hat\tau_n(u,v)dudv \tag{6.2}$$

as estimate for the asymptotic variance of $\hat\tau_n^{(LSS)}$, that is

$$\hat\sigma_n^2=\frac{4}{n}\sum_{i=1}^n (V_{ni}-\overline{V}_{n\cdot})^2.$$

A corresponding estimate $\hat\sigma_{appr}^2$ of the asymptotic variance of the statistic $\sqrt{nh_1}\ \hat\tau_{appr}$ is obtained by replacing the integration in (6.2) by its Riemann

$n \setminus \theta$	0.0	0.5	1.0	2.0
50	$3.452 \cdot 10^{-2}$	$9.281 \cdot 10^{-3}$	$4.962 \cdot 10^{-3}$	$1.093 \cdot 10^{-2}$
100	$1.674 \cdot 10^{-2}$	$2.748 \cdot 10^{-3}$	$2.487 \cdot 10^{-3}$	$2.282 \cdot 10^{-3}$
200	$9.608 \cdot 10^{-3}$	$9.396 \cdot 10^{-4}$	$1.627 \cdot 10^{-3}$	$6.298 \cdot 10^{-4}$

TABLE 1
Simulated mean squared error of the estimate (5.3), when the underlying copula is the Clayton copula defined in (6.1).

approximation. In Table 2 we show the simulated probabilities

$$P\left(\frac{\sqrt{n}(\hat{\tau}_{appr} - \tau)}{6\hat{\sigma}_{appr}} \leq u_{1-\alpha}\right) \approx 1 - \alpha, \tag{6.3}$$

where $u_{1-\alpha}$ denotes the $(1-\alpha)$-quantile of the standard normal distribution. The sample is $n = 100$ and $n = 200$, the bandwidth is again chosen as $h = n^{-3/10}$ and the underlying copula is the Clayton copula. We observe a reasonable approximation by the limit distribution in all cases under consideration.

$1-\alpha$	$n \setminus \theta$	0.0	0.5	1.0	2.0
90%	100	0.885	0.878	0.891	0.916
	200	0.891	0.903	0.984	0.912
95%	100	0.962	0.939	0.964	0.964
	200	0.942	0.951	0.958	0.961

TABLE 2
Simulated probabilities of the form (6.3) for the Clayton family.

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