

#### Dimensional Control and Formability in Impact Forming

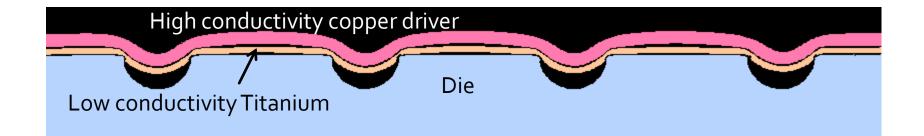
A simulation perspective

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#### Motivation



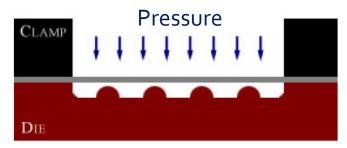
- Dynamics of impact
- Shape fidelity & frictional effects
- Rebound characteristics (Magnetic pressure effect)
- Constitutive and failure laws



## **Boundary conditions**



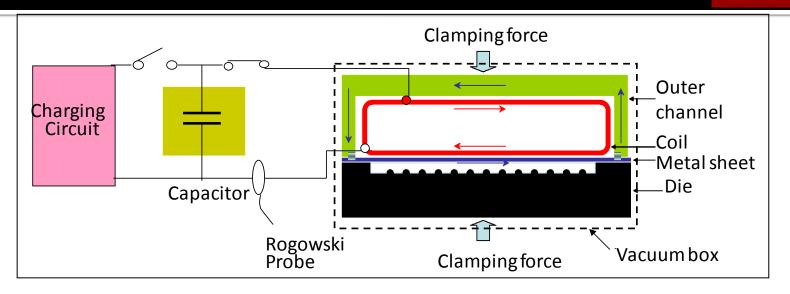
- Uniform pressure applied on copper driver section
- Velocity from model compared against experimental velocity (PDV)
- Mechanical deformation only
- Computationally efficient electro-magnetics decoupled from solver



Schematic

#### Experiments

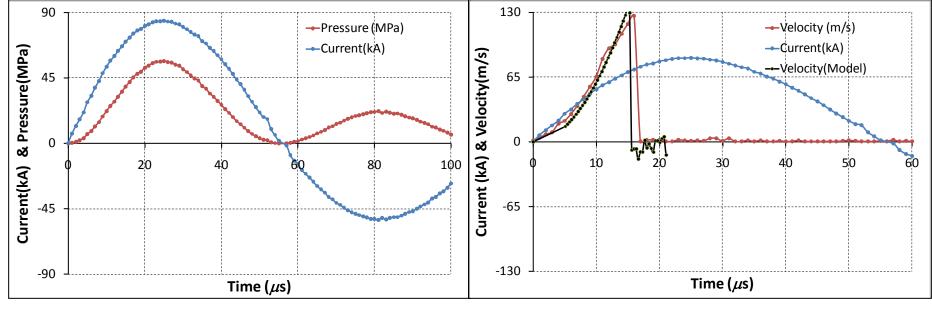




- Titanium sheet is formed using copper as driver
- Velocity of flyer is measured using Photon Doppler Velocimeter system
- Energy range 1.6 to 6.4 kJ, Vacuum 100 Torr Standoff 2 mm, Peak velocity range 100-300 m/s



#### Model variables@ 3.2 kJ



#### **Input current**

**Output velocity** 

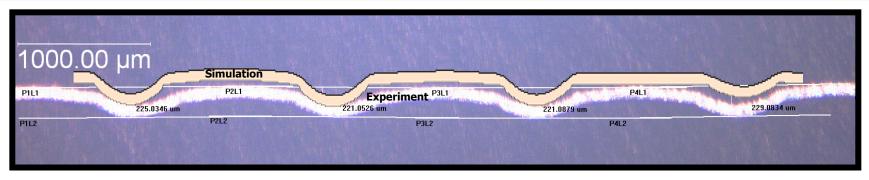
#### Strains @ 3.2 kJ



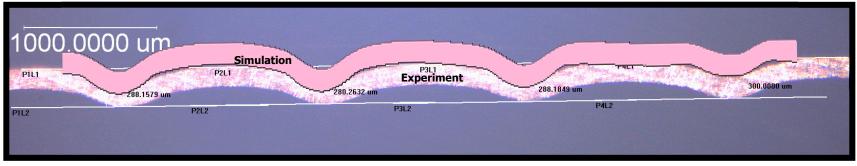


#### **Model validation**





Titanium after impact @ 3.2 kJ

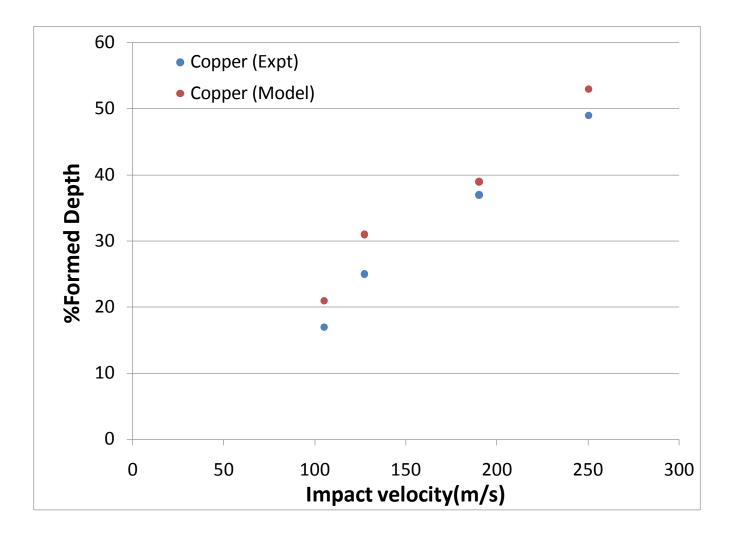


Copper Driver after impact @ 3.2 kJ

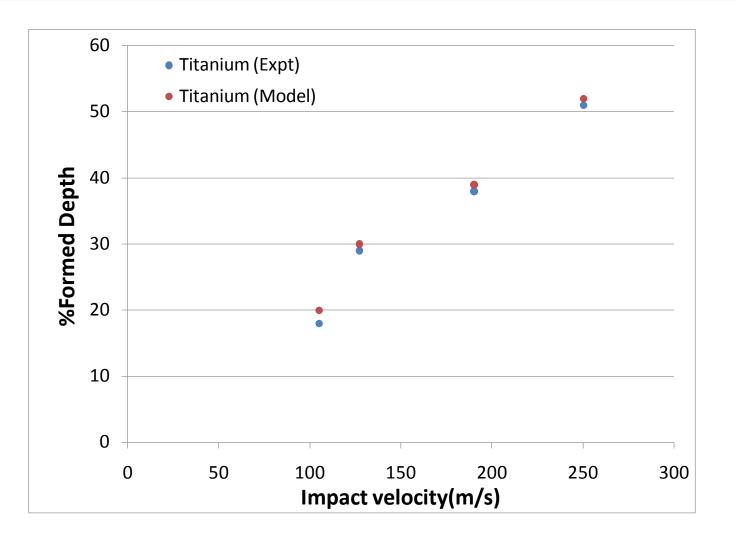
\*Courtesy: Huimin Wang, EMF group

## Form depth (Copper)





## Form depth (Titanium)

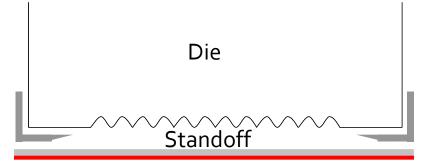


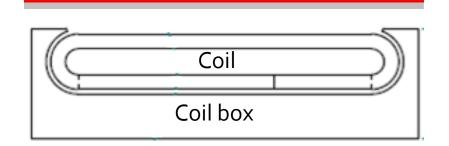


#### **Interface Effects**

\*Interface = Mating sides between driver and forming material\*

- "Sticking" at interface between driver and work piece
- To avoid sticking placed different media in interface
- Media included paper, carbon copy paper, and vacuum grease
- Sticking eliminated, however shearing resulted



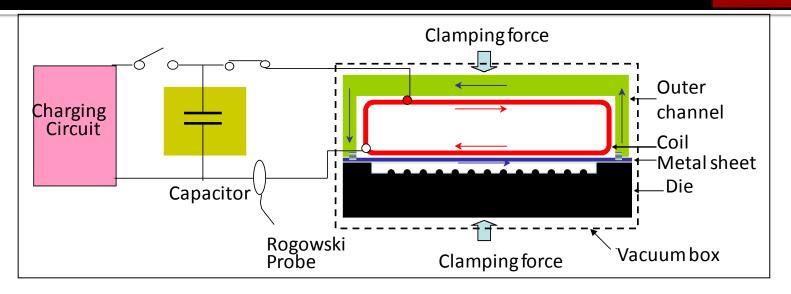


Interface surfaces

\*Courtesy: Kristin Banik, 2008

#### Experiments





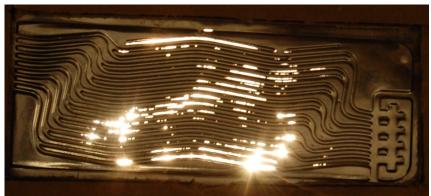
- 304 Steel sheet is formed using copper as driver
- Interface of study is the mating surface between driver sheet and workpiece
- Energy 4 kJ, Vacuum 90 Torr, Peak velocity 205 m/s Standoff distance 3mm

#### Results

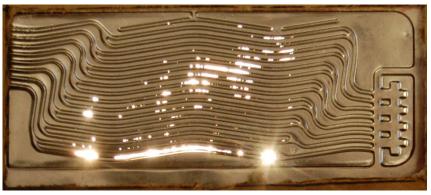




No interface material



**Carbon Paper** 



Paper

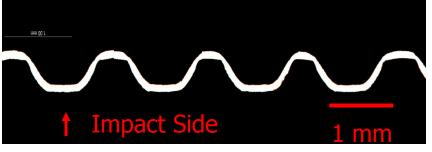


Vacuum Grease

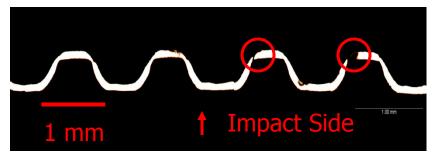
Samples are illuminated from behind

#### **EMF Plate Cross Sections**

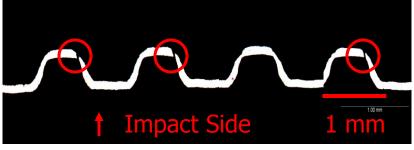




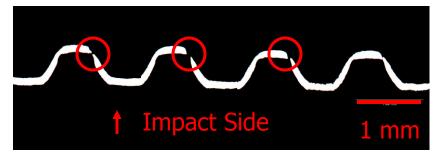
No interface material



**Carbon Paper** 



Paper

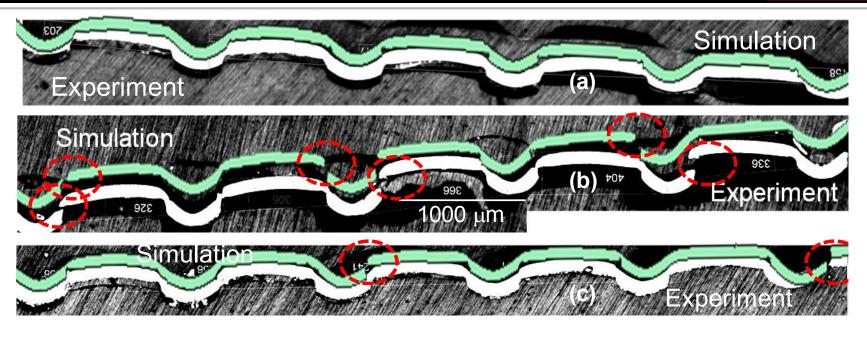


Vacuum Grease

Peak Velocity 205 m/s

### **Friction calibration**

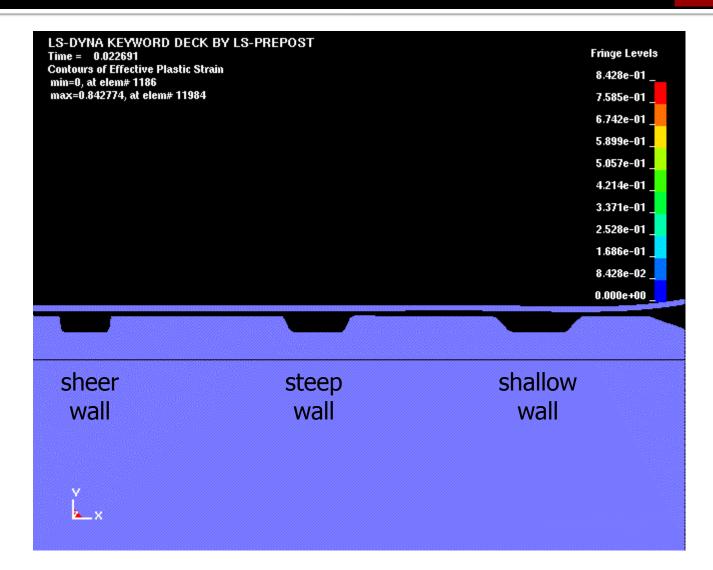




- (a)No lubrication (μ=0.5)
- (b)Lubrication between Copper and SS201 (austenitic steel) (μ=0.5 / μ=0.05)
- (c)Lubrication between all interfaces (μ=0.05)

## No Lubrication (µ=0.5)





## Lubrication (µ=0.05)





## Entry angle (Friction 0.5)



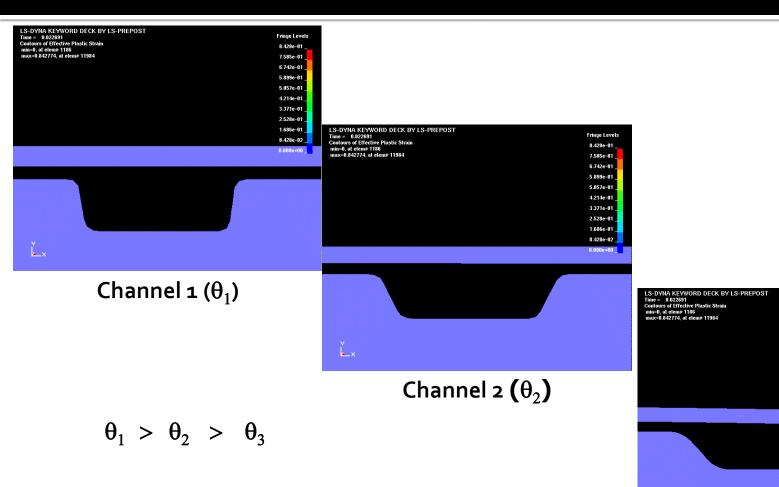
Fringe Levels

8.428e-01

7.585e-01 6.742e-01 5.899e-01 5.057e-01

4.214e-01 3.371e-01 2.528e-01

1.686e-01 8.428e-02

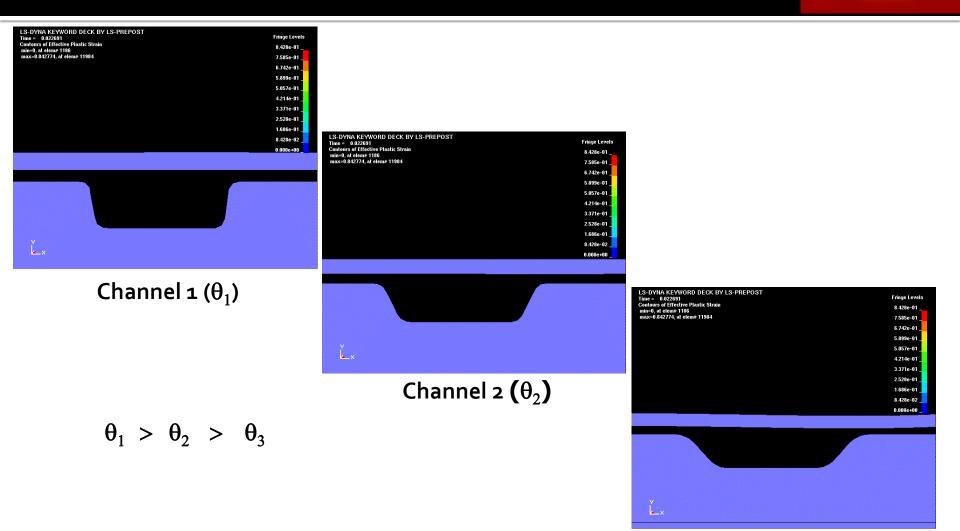


Channel 3 ( $\theta_3$ )

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## Entry angle (Friction 0.05)





Channel 3 ( $\theta_3$ )



## Shape fidelity

#### Experiments





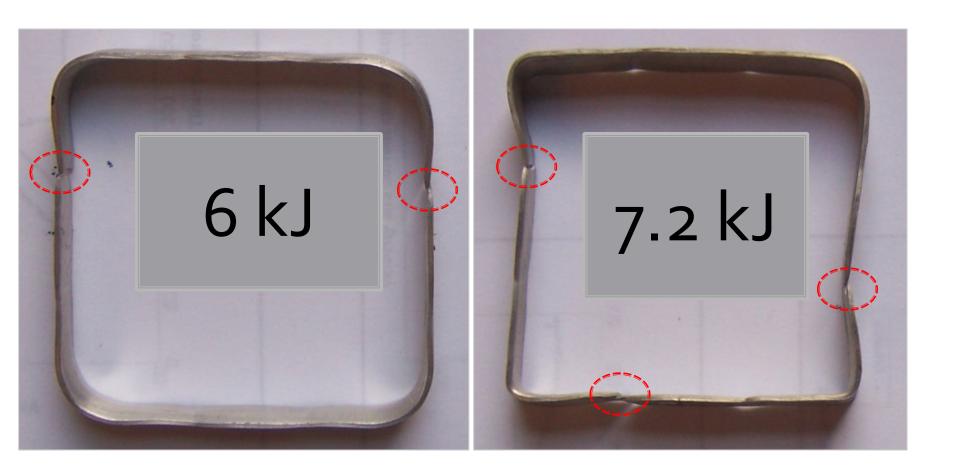
Ring constrained in square

Cylindrical coil

- Aluminum rings are formed without any driver
- Velocity of flyer is measured using Photon Doppler Velocimeter system
- Energy range 6 to 8 kJ, Standoff 2 mm, Peak velocity range 100-200 m/s

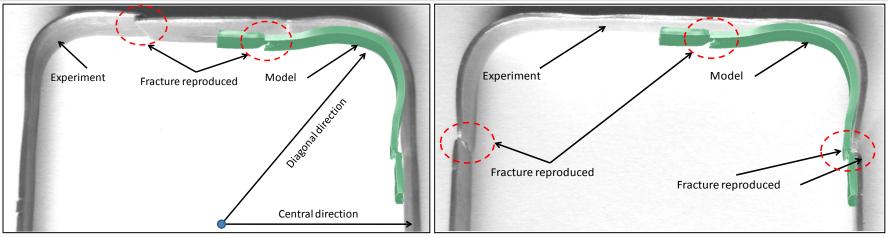


## **Ring specimens after impact**



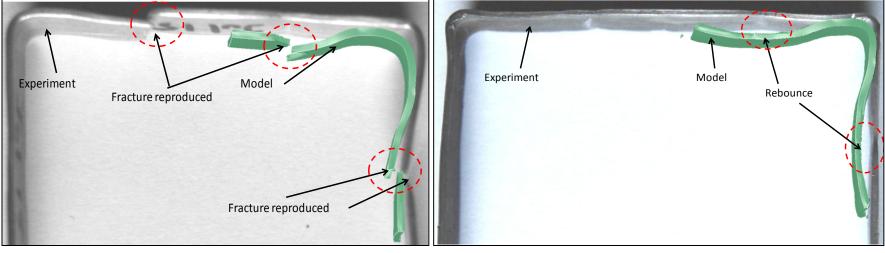
## Model vs. Experiment





#### Energy 5.6 kJ

Energy 6 kJ

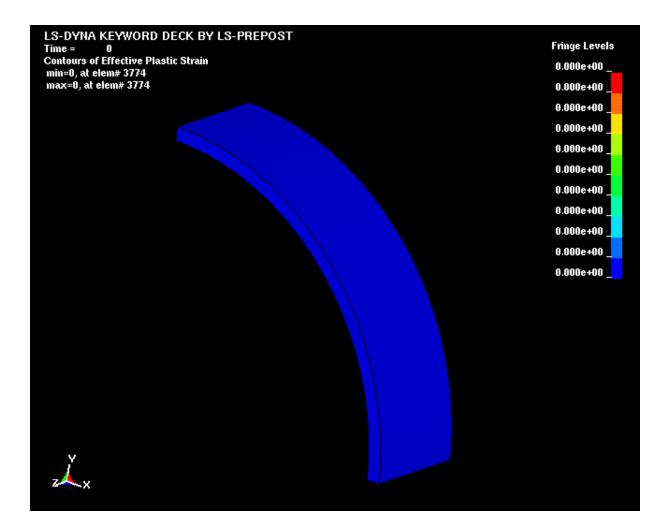


Energy 6.72 kJ

Energy 7.2 kJ

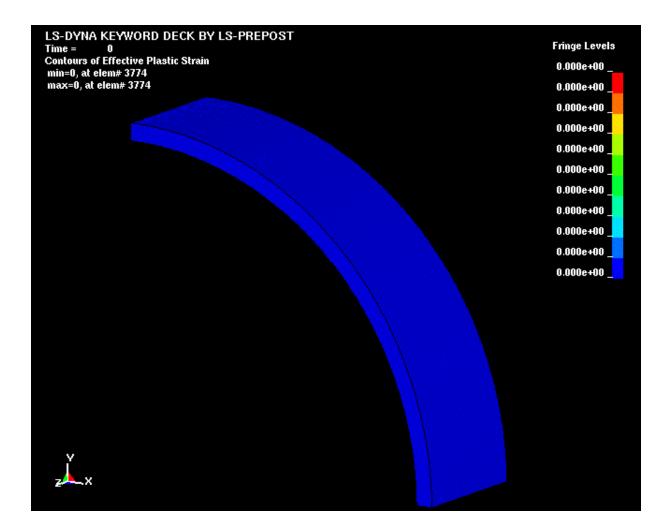
## **@ 6 kJ**





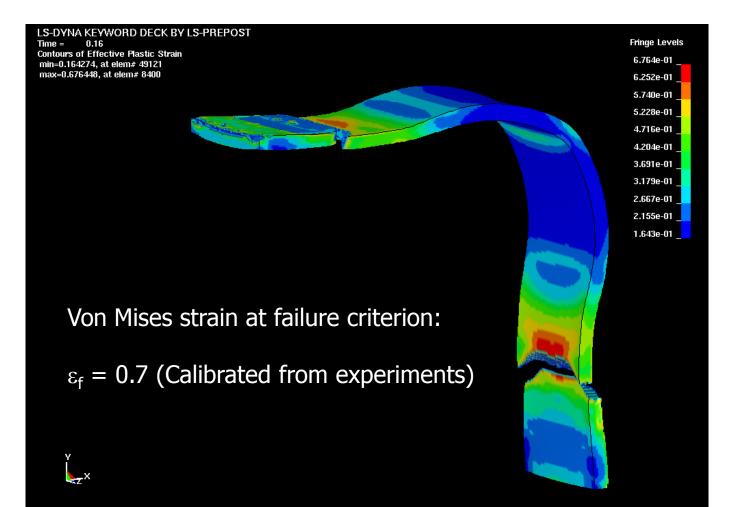
# **@ 7.2 kJ**





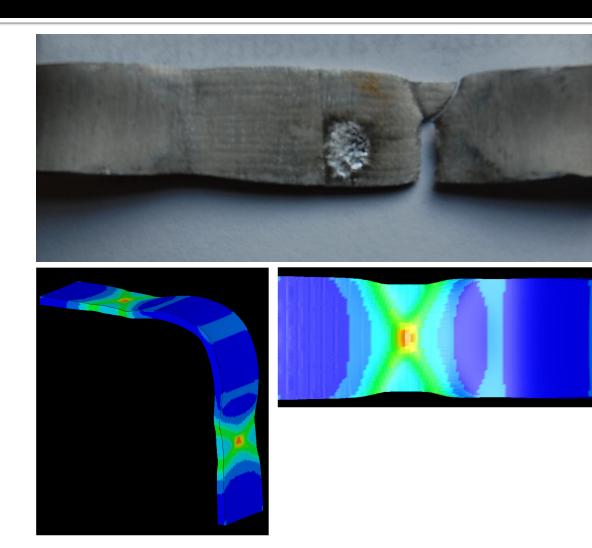
#### **Failure laws**

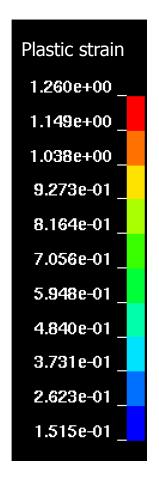




#### Fracture mode

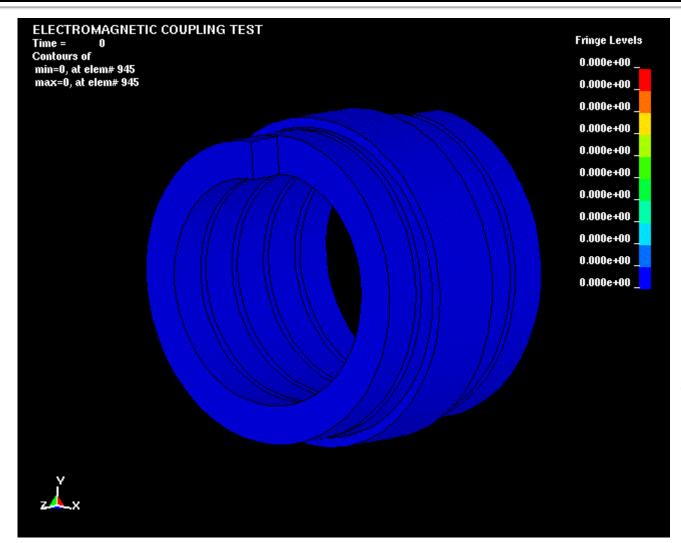






## **Effect of magnetic pressure**





Note: Magnetic pressure restores shape

#### Conclusions



- Friction plays a critical role in influencing formed product quality
- Mechanical simulation shows exaggerated rebound.
  Electromagnetic simulation shows realistic rebound
- Magnetic pressure wave stabilizes the ring into the square cavity minimizing rebound
- Higher velocities diffuse plastic strains through the entire sample thus preventing necking
- Channel entry angle influences formability and welding

## Acknowledgements



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