

## Modelling Pulse Magnetic Welding Processes– an Empirical Approach

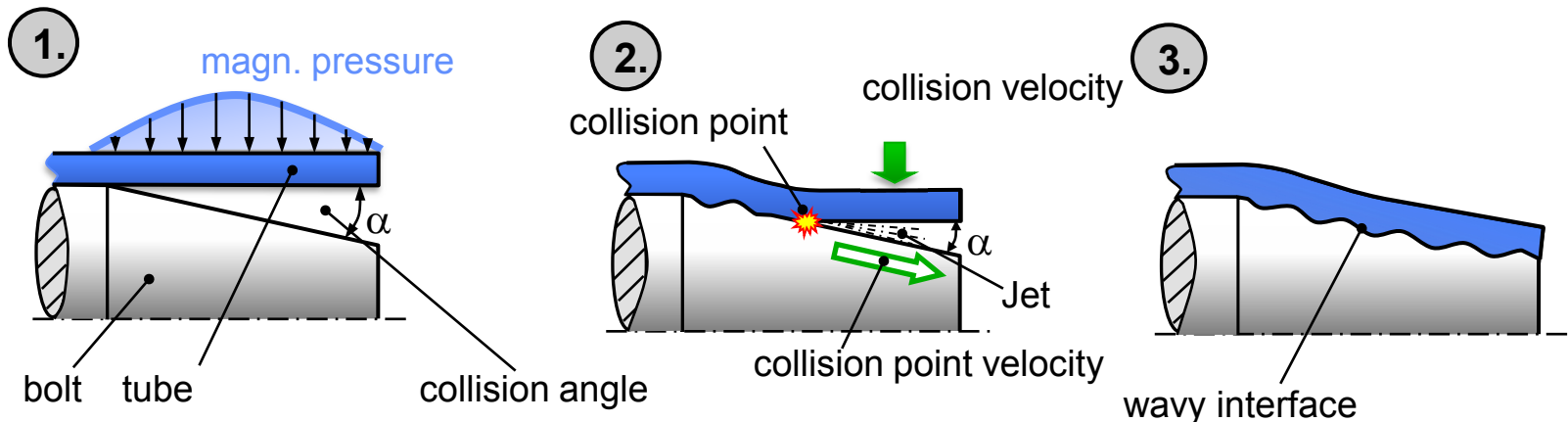
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## The Process

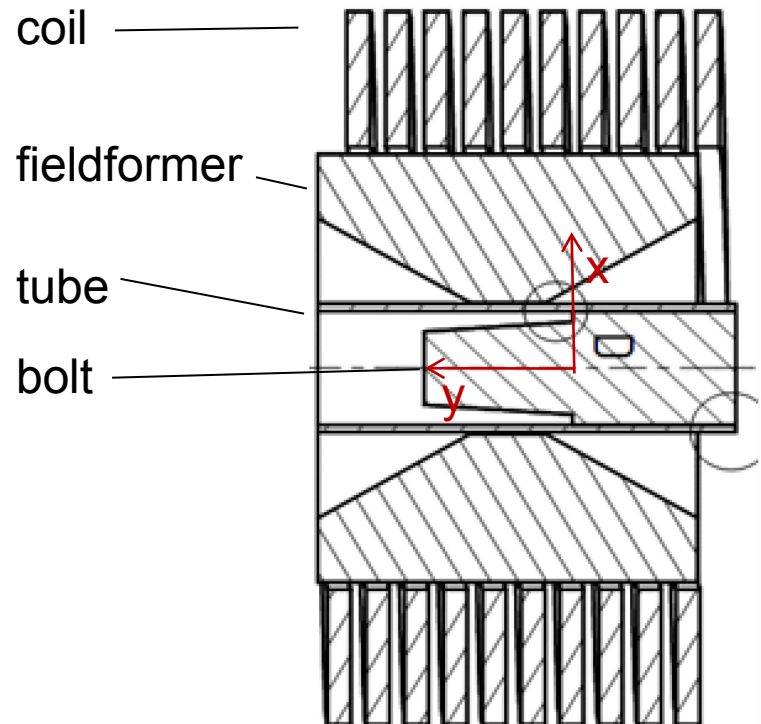
1. • Due to magnetical pressure, the tube is accelerated to the center
2. • High pressures at the collision point are developing  
• A materialjet is created at the collision point.
3. • Material within the contact zone changes to a highly viscous state  
• Formation of a wavy interface



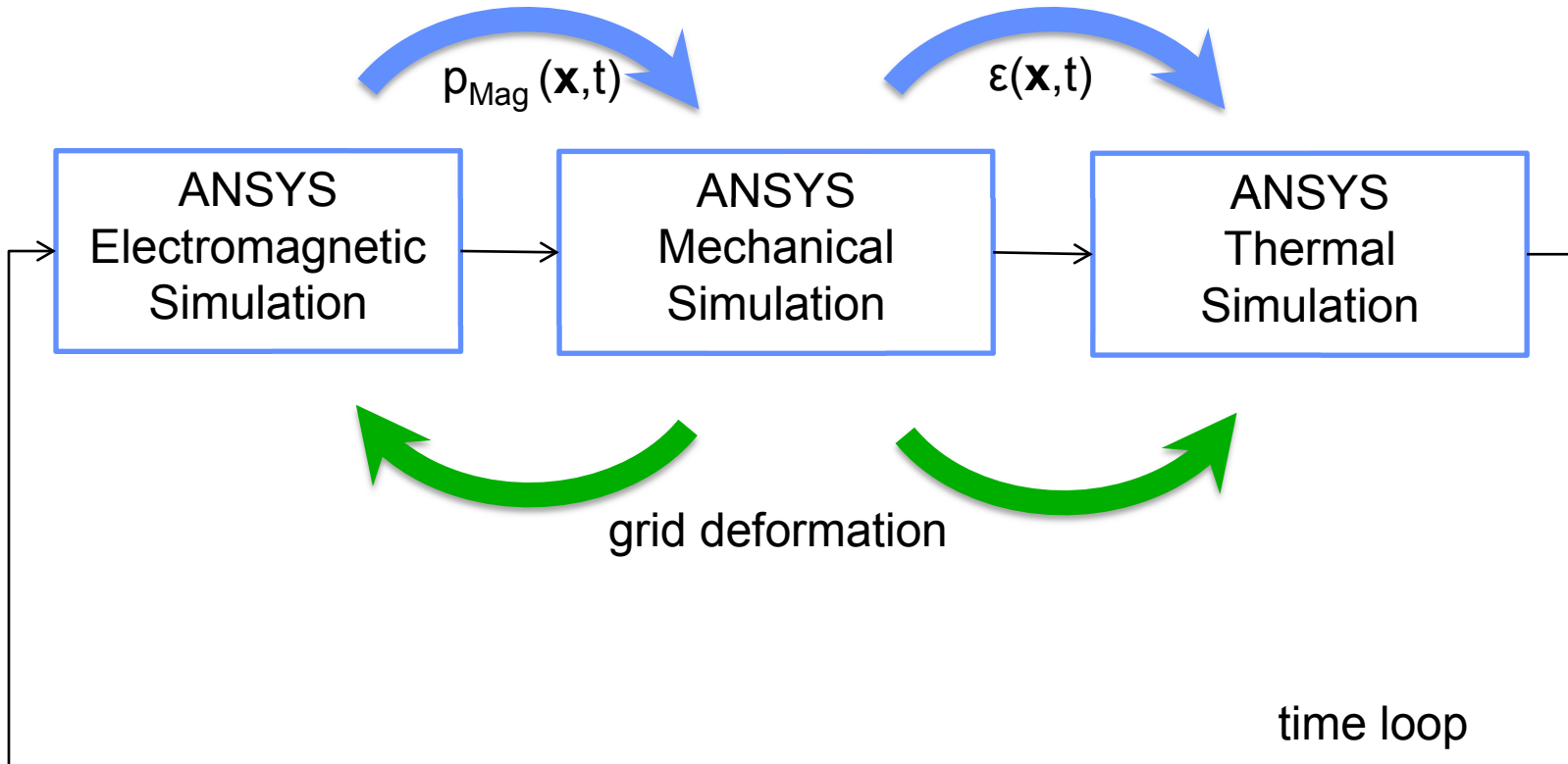
## Experiments

Properties EN AL6063	Value
Specific Resistance	$3,3 \cdot 10^{-8} \Omega \text{ m}$
thermal conductivity	$201 \text{ W m}^{-1}\text{K}^{-1}$
specific heat capacity	$898 \text{ J kg}^{-1} \text{ K}^{-1}$
thermal expansion coefficient	$23,5 \cdot 10^{-6} \text{ K}^{-1}$
permeability $\mu$	$1 \mu_0 = 1,2566 \cdot 10^{-6} \text{ H m}^{-1}$

Parameter	Value
Capacity	$240 \mu\text{F}$
Inductivity	$1,966 \mu\text{H}$
Charging Energy	7, 8 and 9kJ
Frequency	7,3 kHz
skinddepth	1,07 mm



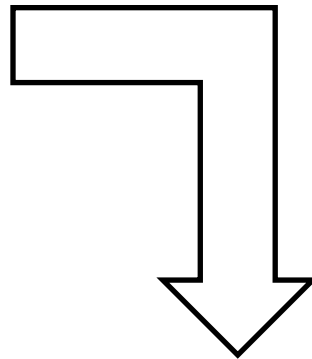
## Simulations – Sequential Coupling of Electrodynamic and Mechanical FEA



## Simulations – Empirical Model

### Possible influences to weldability:

- $\alpha$  inclination-angle,
- $v_{\perp}$  collision point velocity,
- $V_{cp}$  collision point velocity,
- $P_{PL}$  plastic work,
- $\varepsilon$  deformation.

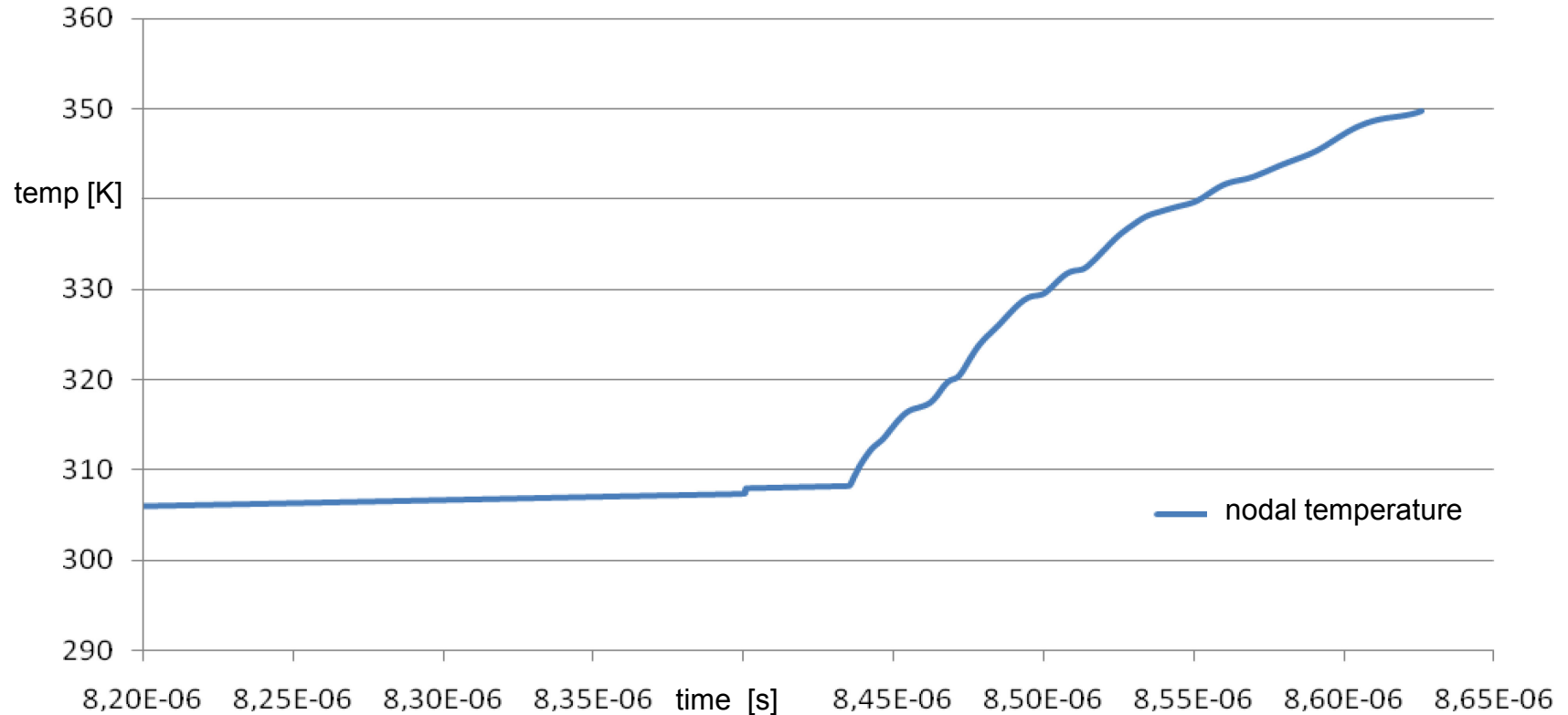


$$B = f(\alpha, v_{\perp}, v_{cp}, P_{PL}, \varepsilon)$$

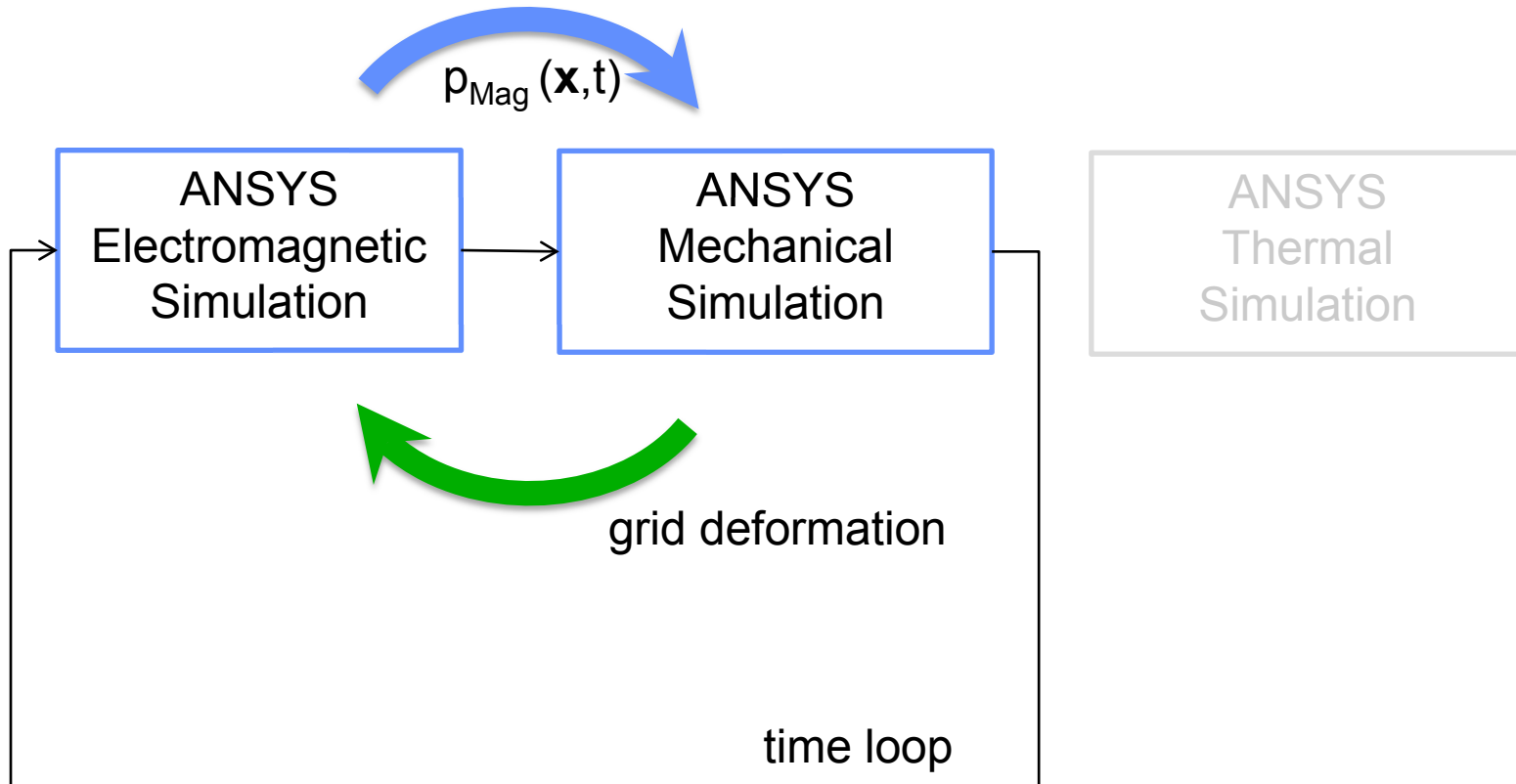
bondage

no bondage

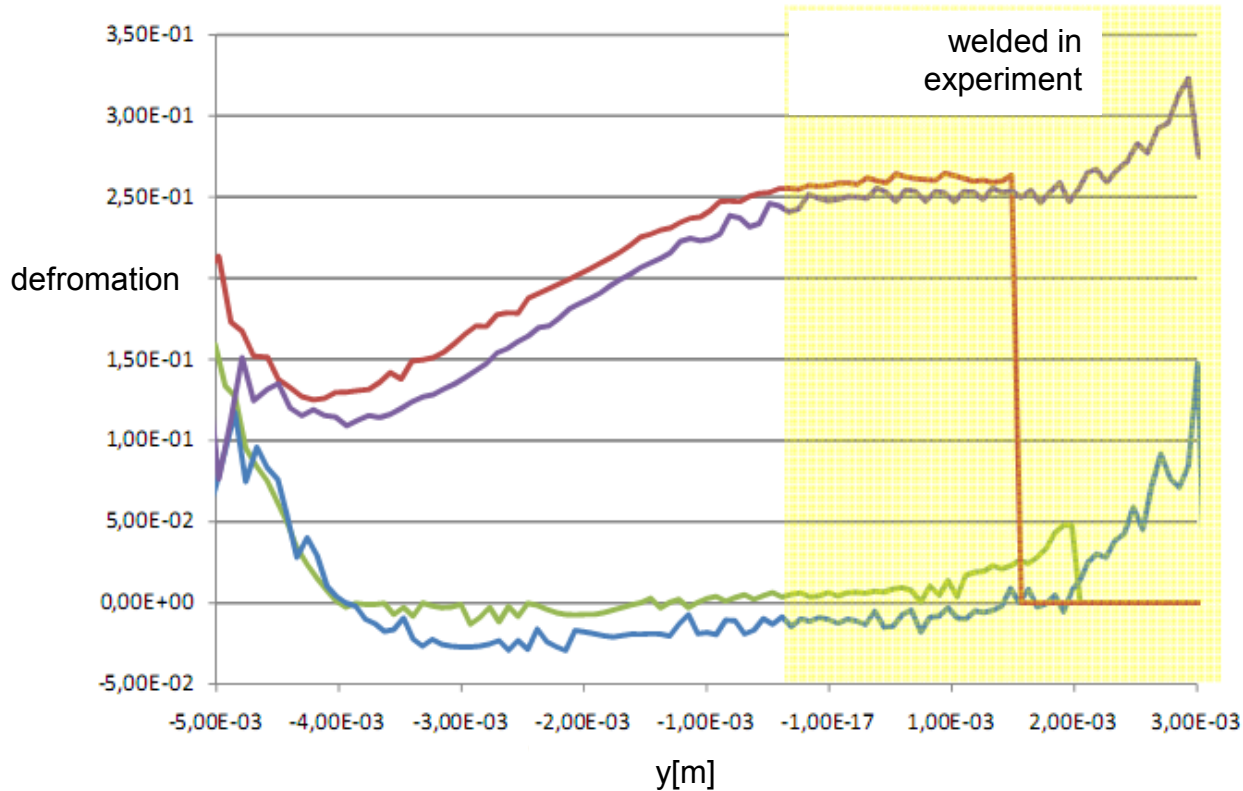
## Simulations – Influence of the Temperature



## Simulations – Sequential Coupling of Electrodynamic and Mechanical FEA



## Model Setup

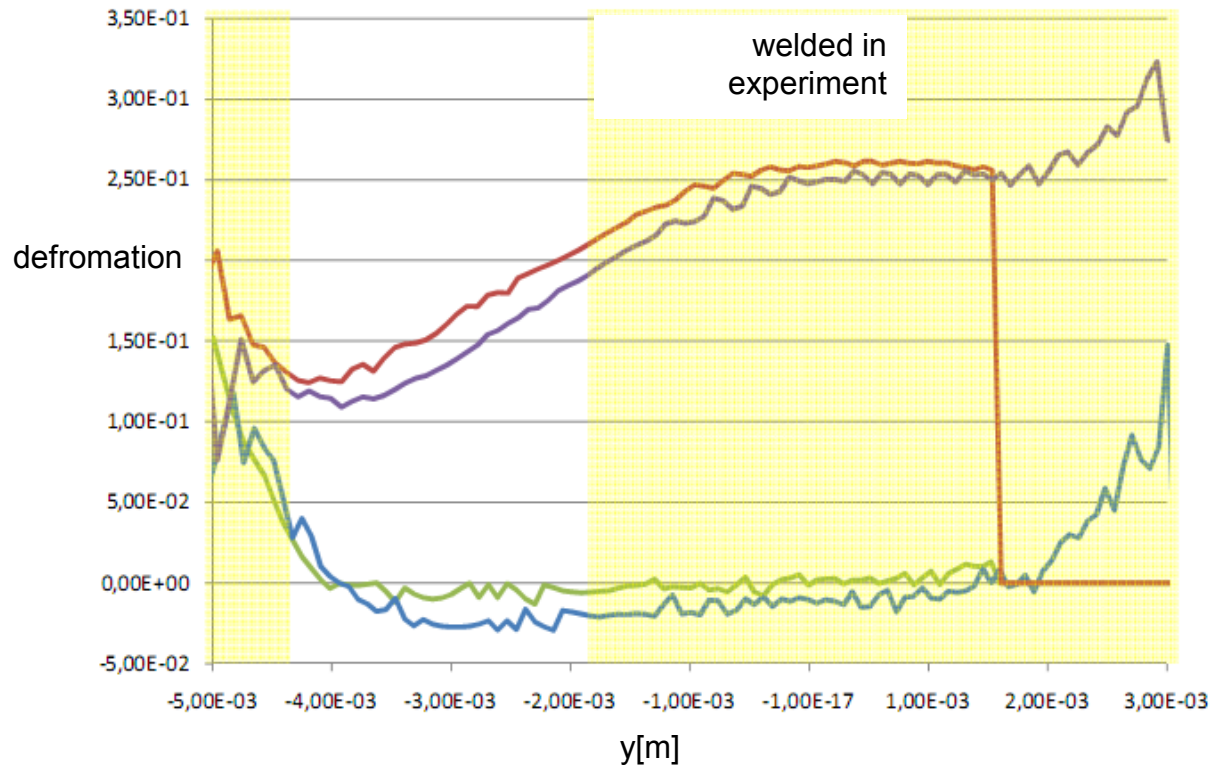


Energy: 7kJ

- Plastic deformation bolt collision time
- Plastic deformation bolt collision time +  $\Delta t$
- Plastic deformation tube collision time
- Plastic deformation tube collision time +  $\Delta t$
- Welded in experiment



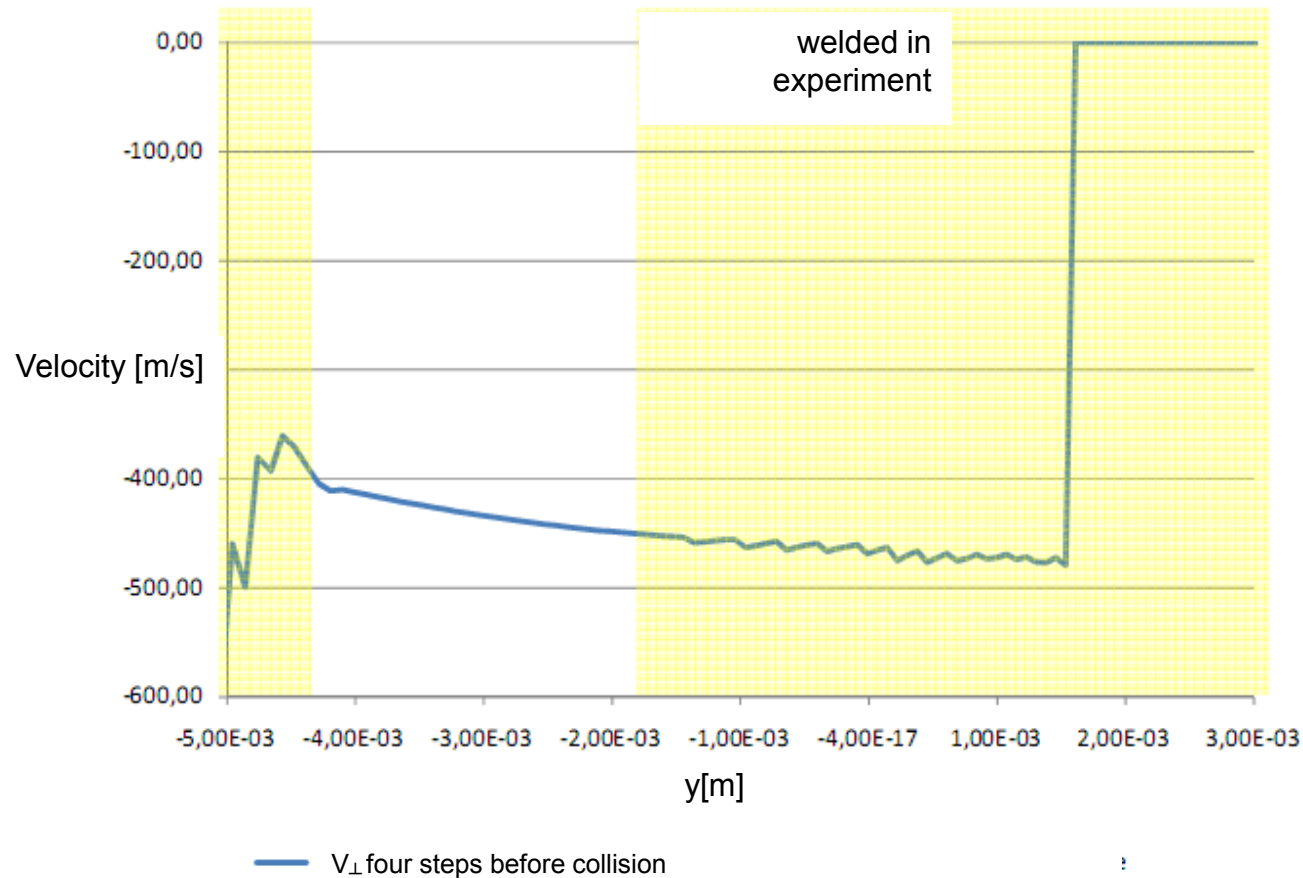
## Model Setup



Energy: 9kJ

- Plastic deformation bolt collision time
- Plastic deformation bolt collision time +  $\Delta t$
- Plastic deformation tube collision time
- Plastic deformation tube collision time +  $\Delta t$
- Welded in experiment

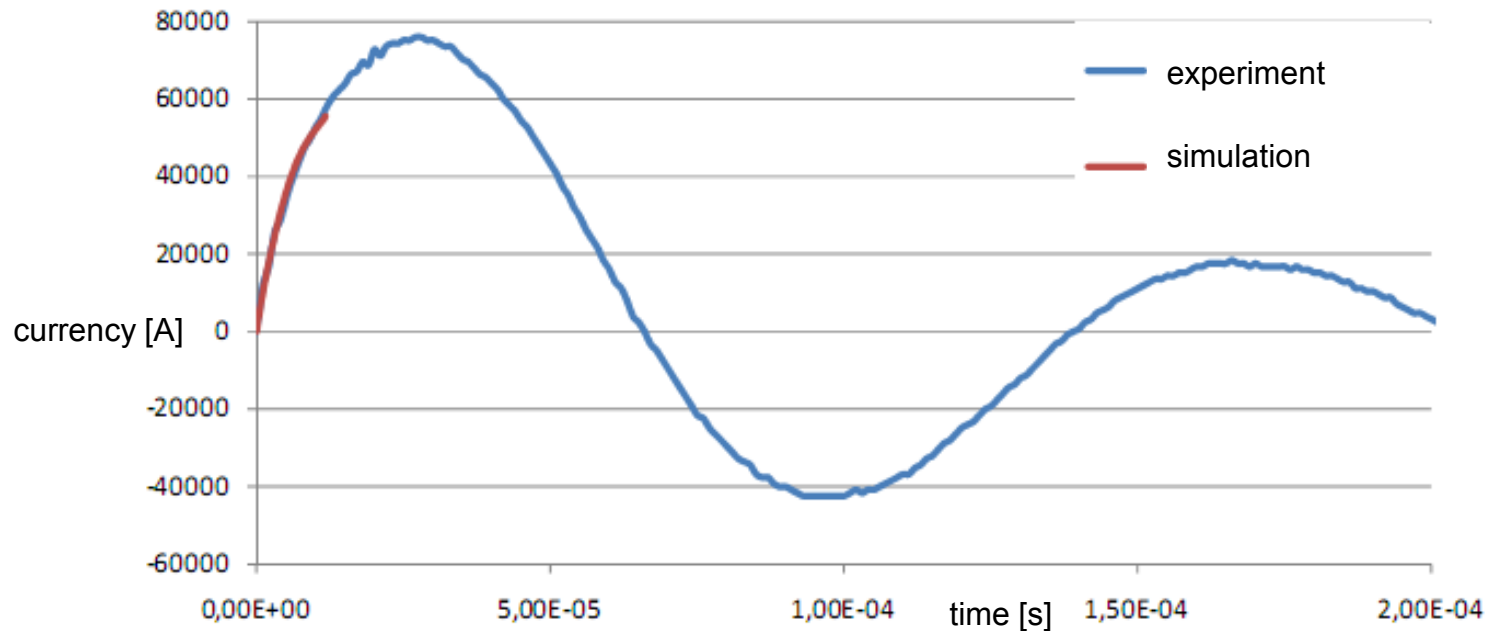
## Model Setup



Energy: 9kJ

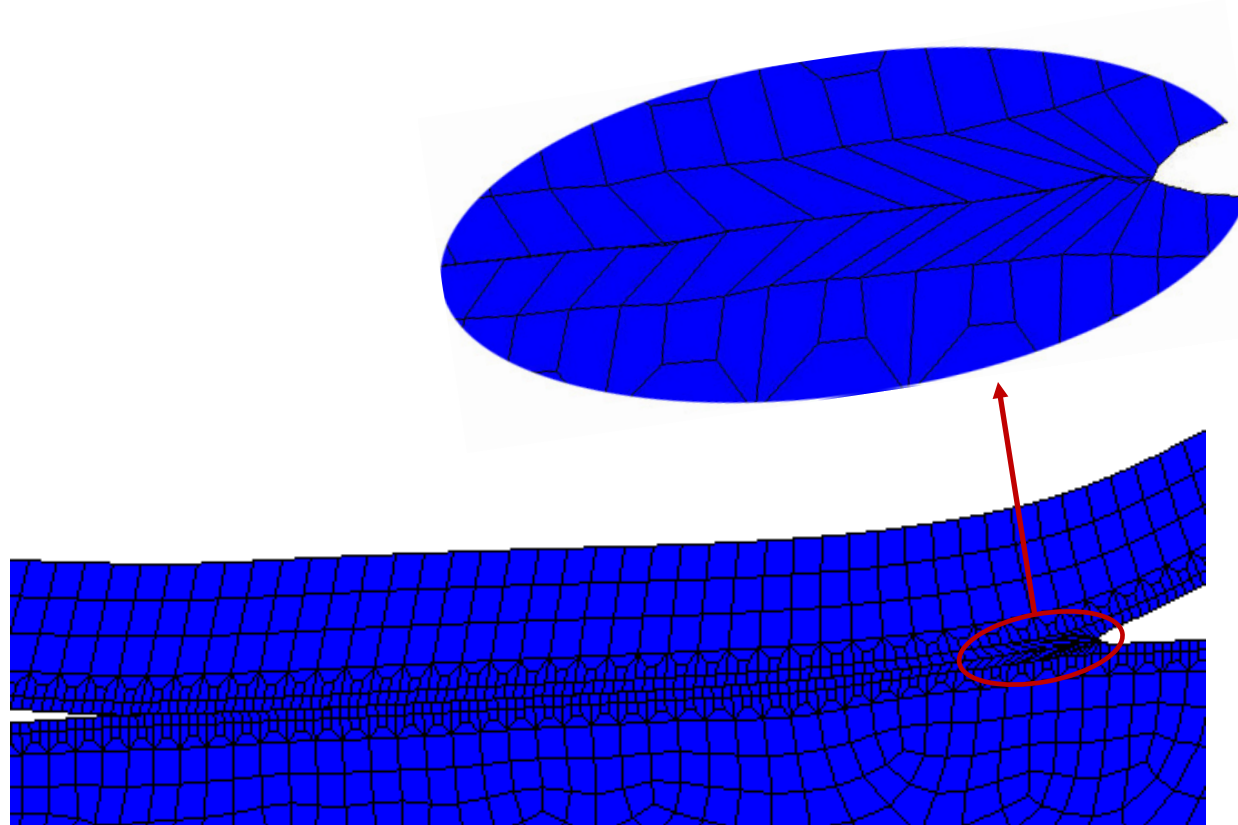
## Results

### Currency distribution of the electromagnetical simulation and measurement

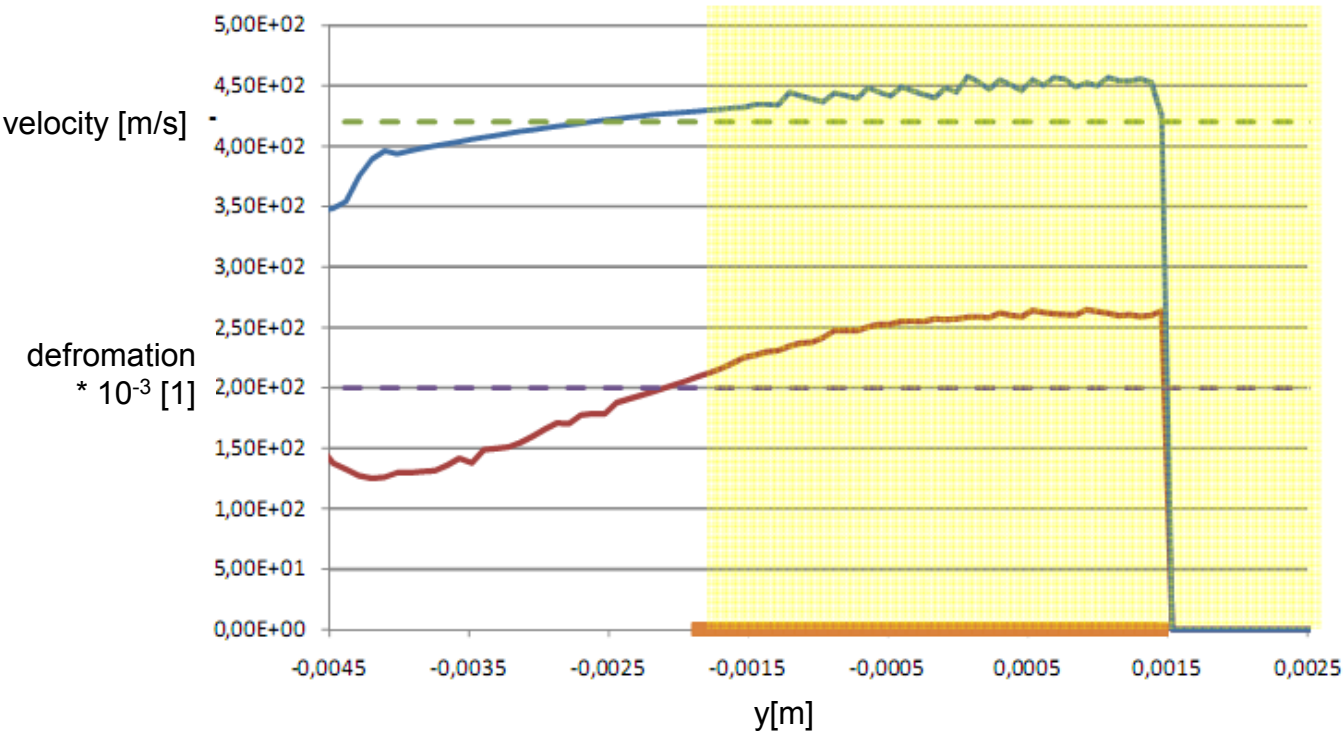


## Results

### Currency distribution of the electromagnetical simulation and measurement



## Results



Energy: 8kJ

- Plastic deformation tube collision time
- collisionn velocity four timesteps before collision
- - - Welding limit collisionn velocity
- - - welding limit Plastic deformation
- Welded in experiment
- Welded in simulation

## Conclusions

- The used FEA – Model was a complete sequential-coupled thermal-electromagnetical-mechanical Simulation.
- Simulations show, that the heat generation due to plastic deformation does not account for the welding process.
- Set up and calibration of a bonding-model for accurate material bonding at the welding-interface
- Reduction of the set of necessary parameters, leaving the normal collision velocity and plastic deformation.

## Outlook

- Further validation is necessary in order to expand the extent of validity as well as the use for additional Materials.
- An open question is the welding behaviour with mixed materials.
- The implicit FEA - software was not designed to calculate big deformations  
→ Making use of explicit FEA – software such as AUTODYN
- Loosening and cracking were not part of the model as well.

## Thank you!

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