

An MPP version of the Electromagnetism module in LS-DYNA for 3D Coupled Mechanical- Thermal-Electromagnetic simulations

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- ◆ General presentation of LS-DYNA.
- ◆ Presentation of the electromagnetism (EM) module.
- ◆ Recent and future developments.
- ◆ Presentation of the MPP version of the EM module.
- ◆ Examples:
 - ◆ Electromagnetic free forming.
 - ◆ Electromagnetic bending.
 - ◆ Rail gun.

Finite element code for non linear transient dynamics

- 2-D and 3-D simulations with explicit/Implicit time integration
- Deformable & rigid bodies
- Numerous element types and formulations
- Around 150 constitutive (material) models
- 14 equations-of-state
- More than 35 contact algorithms
- Coupled thermal analysis
- Coupled fluid/structure analysis (Euler/ALE/Lagrange element formulations)
- Smooth Particle Hydrodynamics (SPH)

- **Automotive**

- Crash
- Airbags
- Occupant safety

- **Aerospace**

- Bird strike
- Blade containment
- Crash

- **Manufacturing**

- Stamping
- Forging
- Casting

- **Structural**

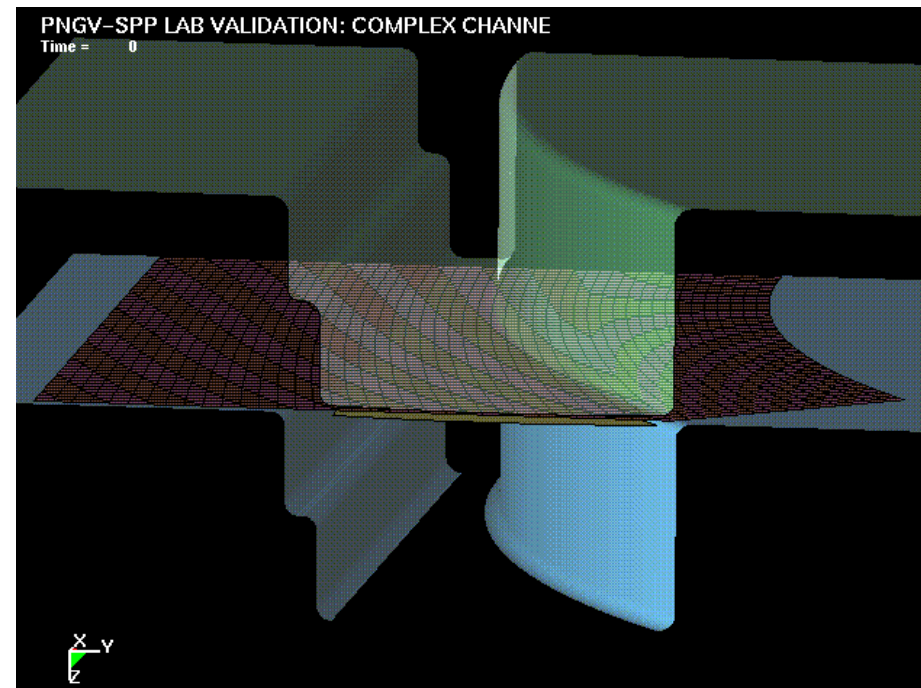
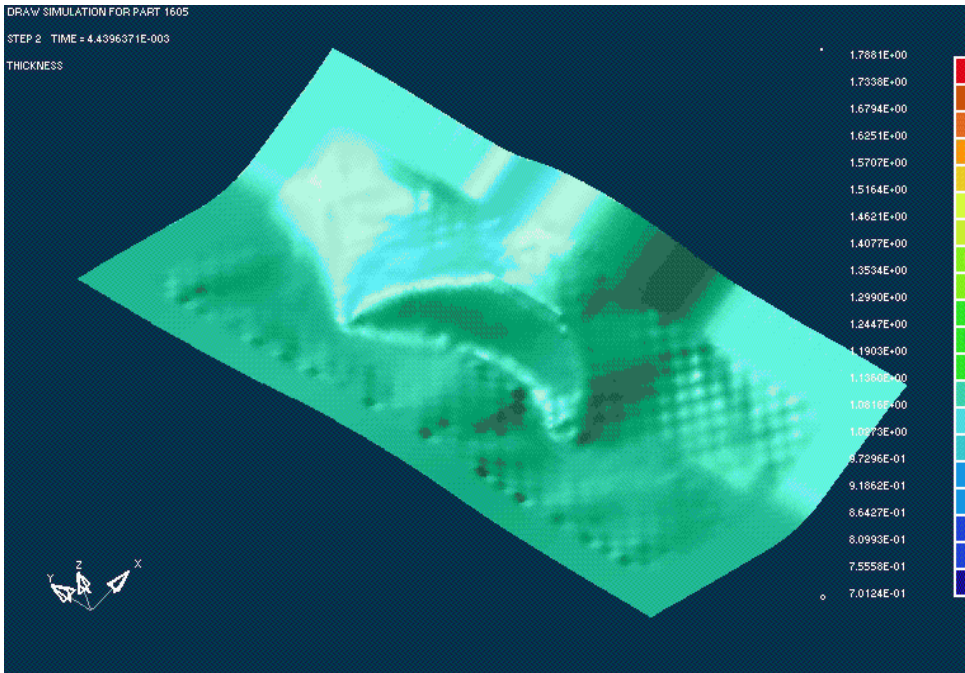
- Earthquake safety
- Concrete structures

- **Electronics**

- Drop analysis
- Package design
- Thermal

- **Defense**

- Weapons design
- Blast response
- Penetration



- ◆ Electromagnetism module for 3D eddy-current problems, coupled with mechanical and thermal solvers (typical applications: magnetic metal forming and welding).
- ◆ Boundary element method in the air coupled to finite elements in the conductor is used to avoid meshing the air.
- ◆ The EM fields, as well as EM force and Joule Heating can be visualized with LSPREPOST.

- **Magnetic metal forming.**
- **Magnetic metal cutting.**
- **Magnetic metal welding (impact welding).**
- **High magnetic pressure generation.**
- **Computation of the stresses/deformations in coils.**

More recently:

- **Induced heating (Joule effect).**
- **Resistive heating.**
- **Electromagnetic contact capability: rail-gun.**

- ◆ MPP version now available.
- ◆ Electromagnetism contact capability now available (rail gun, ...).

Future:

- ◆ Extension of the module to tetrahedral, wedges elements, triangular faces, as well as shells.
- ◆ Introduction of other solvers than eddy-current (magnetostatics,...).
- ◆ Mesh adaptivity.

- **Allows sharing the computation as well as the memory between several processors.**
- **Large gains in run time.**
- **Makes it possible to simulate much larger cases.**
- **Especially true for the BEM part of the EM solver which is the most demanding both in memory and CPU.**

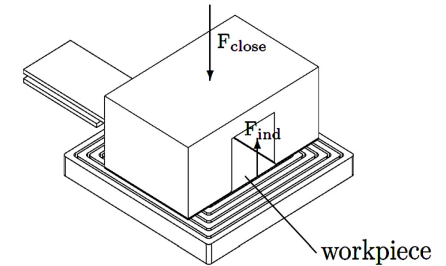
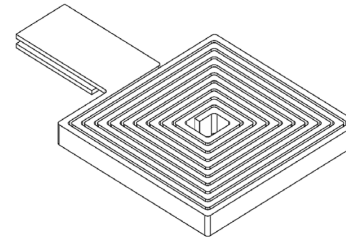
Run time vs # procs for typical EMF case:

#proc	1	2	4	8	16	32	64
Run time	24h16mn	12h16mn	6h28mn	3h56mn	2h29mn	1h36mn	1h09mn

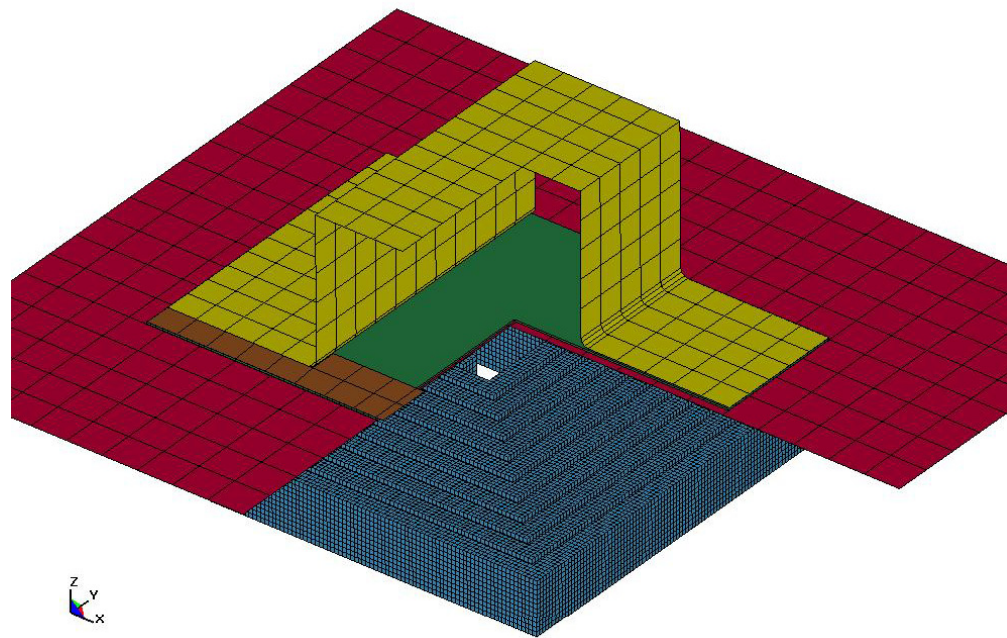
Maximal mesh (#elements) size vs # procs (typical)

#proc	1	8
# elem	100,000	500,000

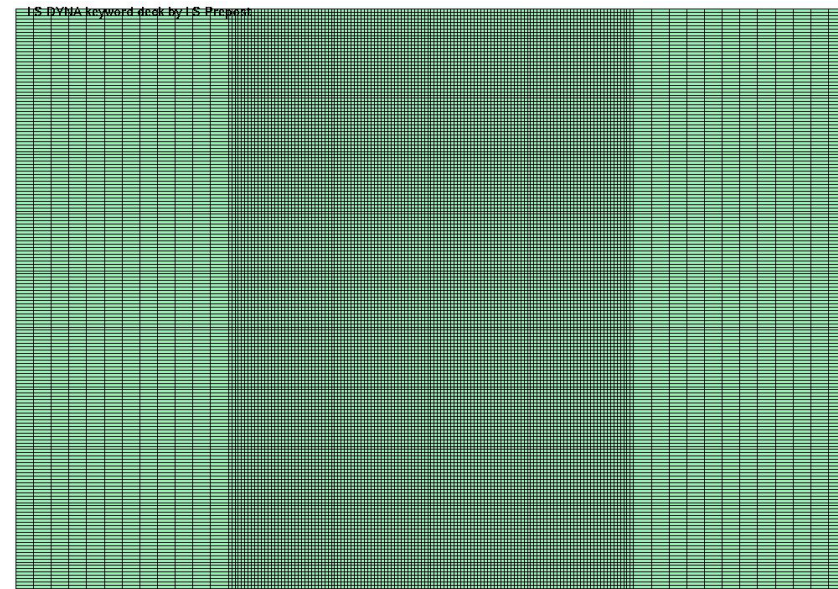
AZ31B magnesium alloy sheet



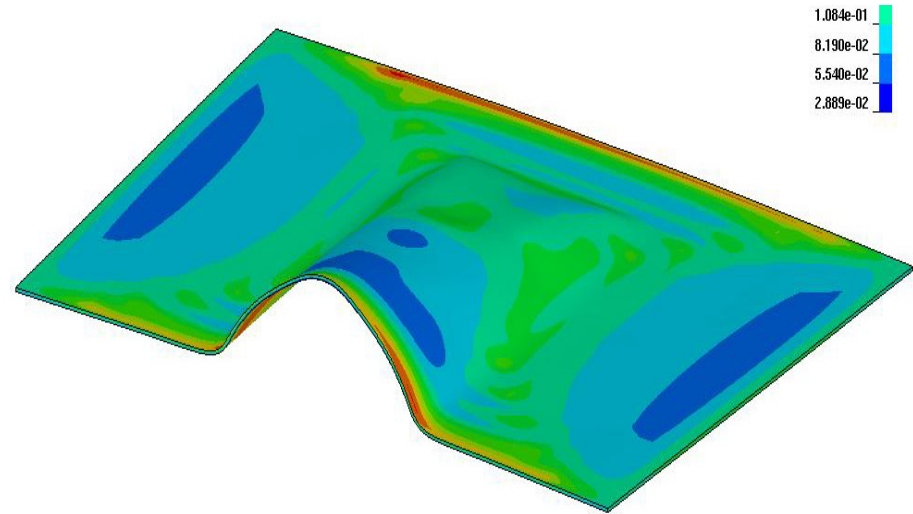
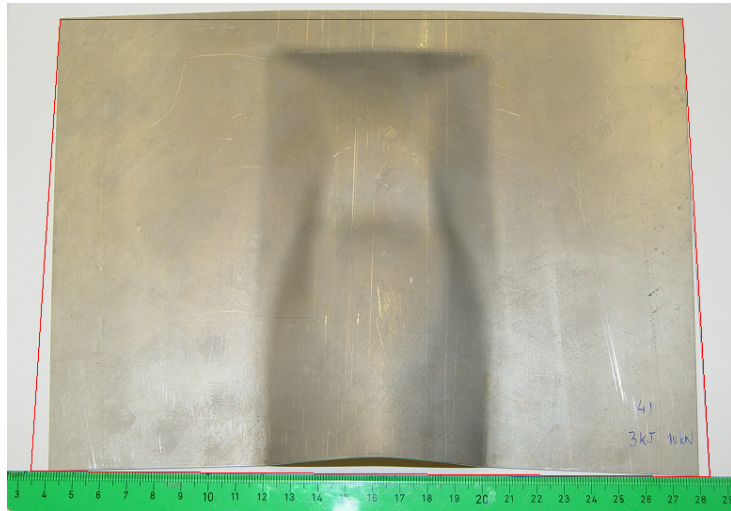
Coil and die used



Mesh (general view- 1/4 represented)



Mesh (sheet)



Num. and Exp. Final shapes

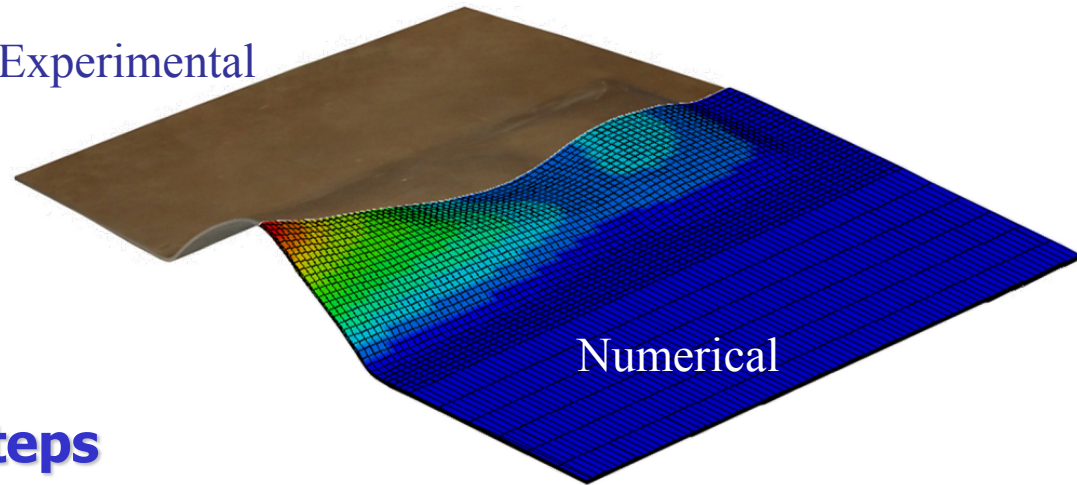
Total run time: 300 μ s

Time steps:

- **Mechanical: 30ns**
- **Thermal: 2 μ s**
- **EM: 1.5 μ s**

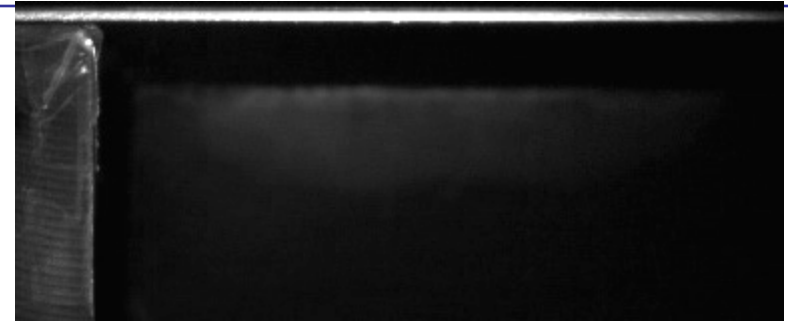
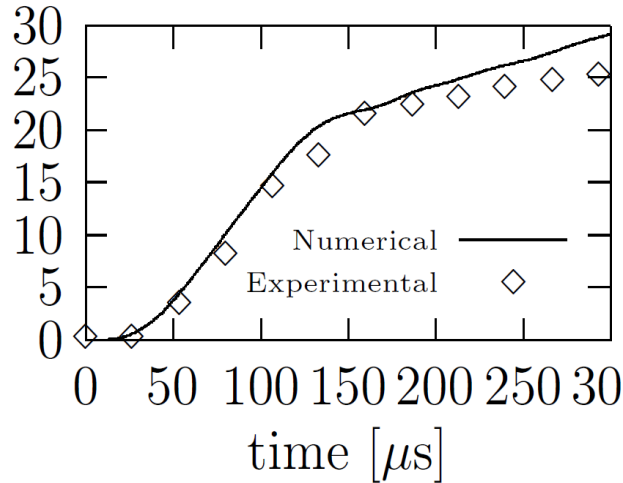
**with FEM and BEM matrices
reassembly every 10 time steps
(=200 EM time step, 20 matrix reassembly)**

Experimental





Displacement z [mm]



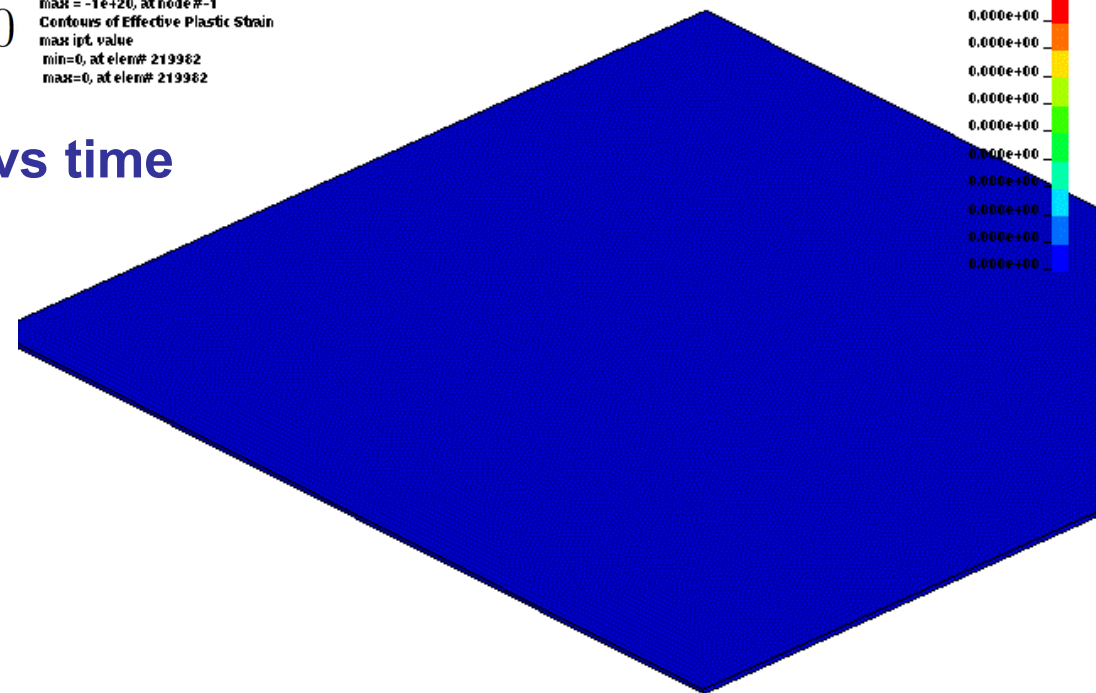
PHOTRON High speed camera

Free Forming AZ31B
Contours of Magnetic field BEM (length magnitude)
min = 1e+20, at node #-1
max = -1e+20, at node #-1
Contours of Effective Plastic Strain
max ipt. value
min=0, at elem# 219962
max=0, at elem# 219962

Fringe Levels
0.000e+00
0.000e+00
0.000e+00
0.000e+00
0.000e+00
0.000e+00
0.000e+00
0.000e+00
0.000e+00
0.000e+00
0.000e+00
0.000e+00

Num. and Exp. Z displacement vs time

**B field
(numerical)**



MPP run time versus number of processors for different mesh sizes

case	mesh1	mesh8	mesh16	mesh32	mesh64
#nodes	39,504	63,759	86,537	131,747	420,478
#elem	28,595	43,568	62,600	98,744	343,224
#BEM P	19,851	36,971	44,279	62,363	147,843
#BEM Q	39,688	73,920	88,532	124,688	295,648

Mesh sizes

# processors	Mesh1	Mesh8	Mesh16	Mesh32	Mesh64
1	24:16	55:41			
2	12:16	27:42			
4	6:28	14:13			
8	3:56	8:49	12:14		
16	2:29	5:15	7:34	15:53	
32	1:36	3:07	4:22	8:57	42:16
64	1:09	2:01	2:46	5:32	26:31

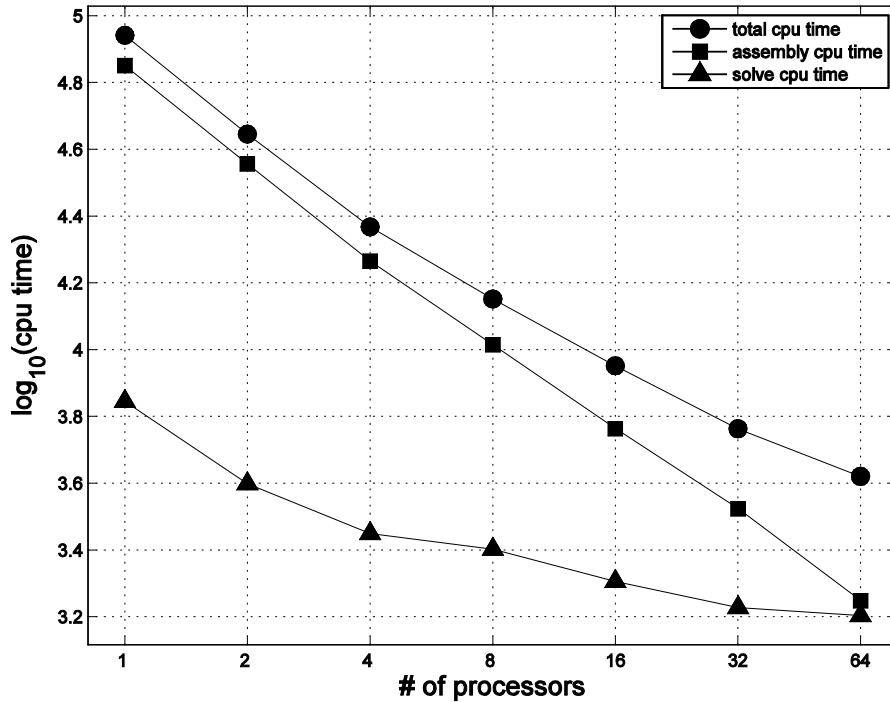
Run time (hours:minutes)



Run time versus number of processors for mesh1 and mesh8

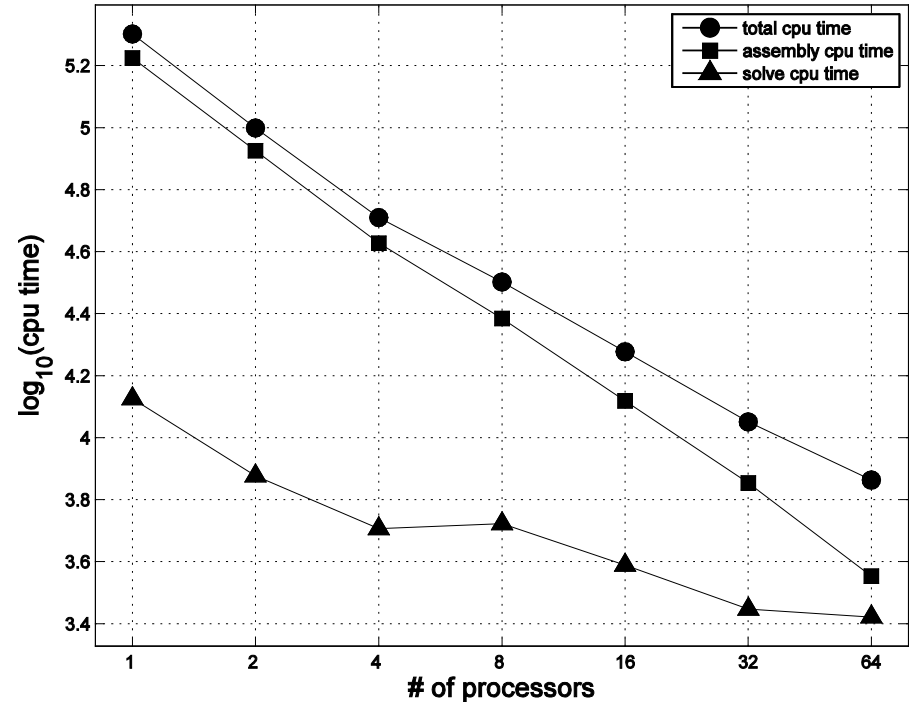
Mesh1

Mesh 1, P is 19851 x 19851 dof



Mesh8

Mesh 8, P is 36971 x 36971 dof



Total time



BEM matrices assembly time



BEM systems solve time

Total time/efficiency vs # of processors for the different meshes

Efficiency defined as:

$$E_p = \frac{p_0 T_{p_0}}{p T_p}$$

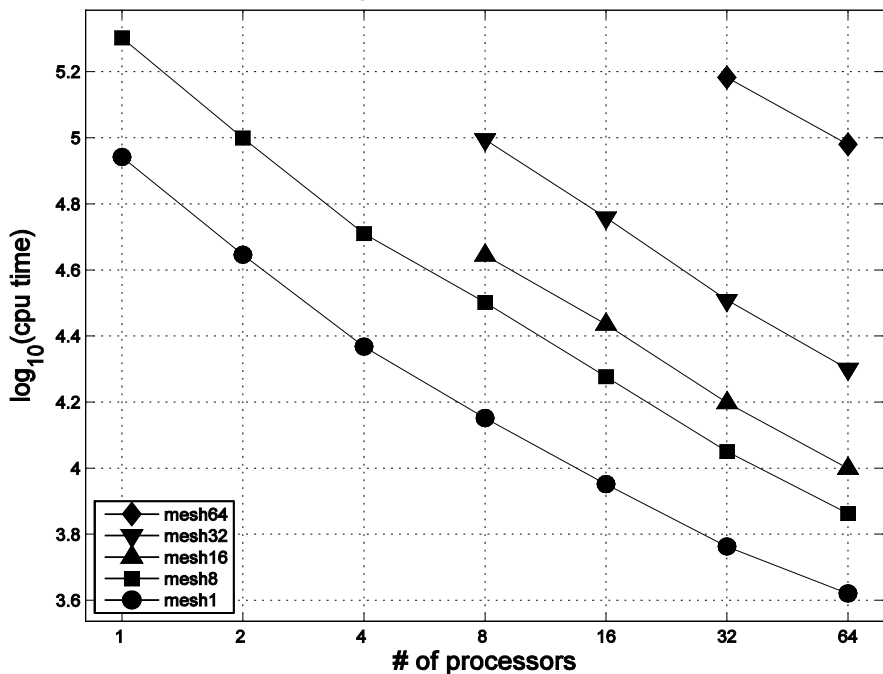
P : number of processor

T_p : run time for p processors

T_{p_0} : run time for p_0 processors (reference)

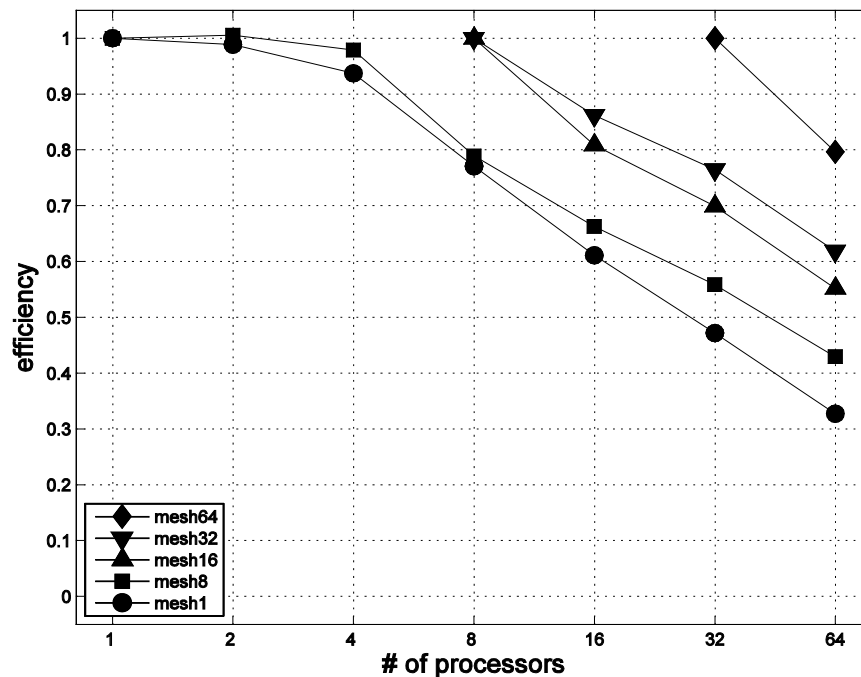
We would like E_p to be as close to 1 as possible

Total cpu times for the five meshes



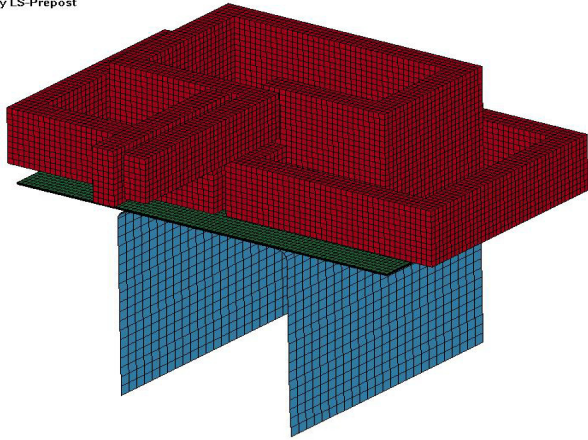
Total CPU time

Total efficiencies for the five meshes

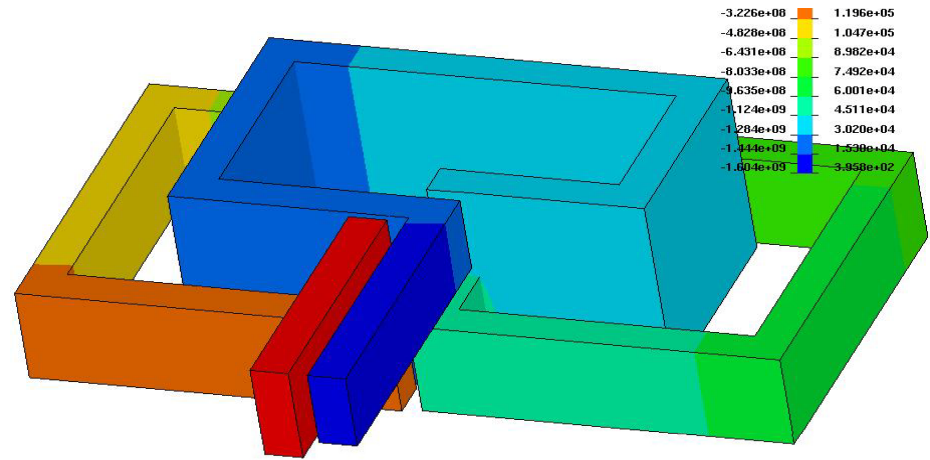


Total efficiency

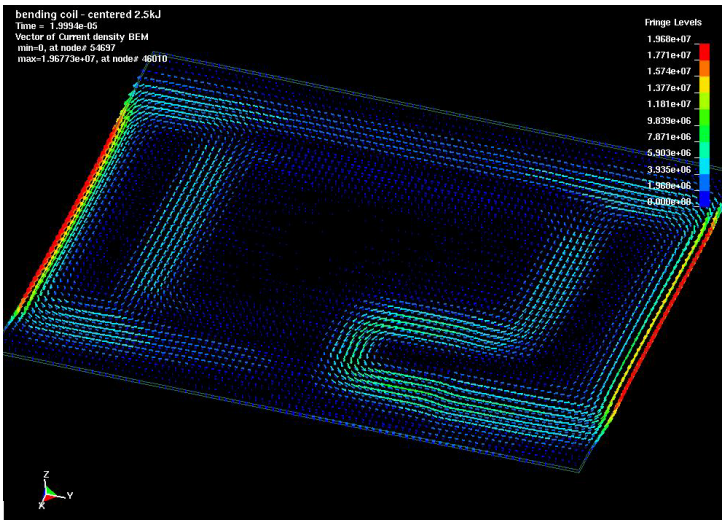
d deck by LS-Prepost



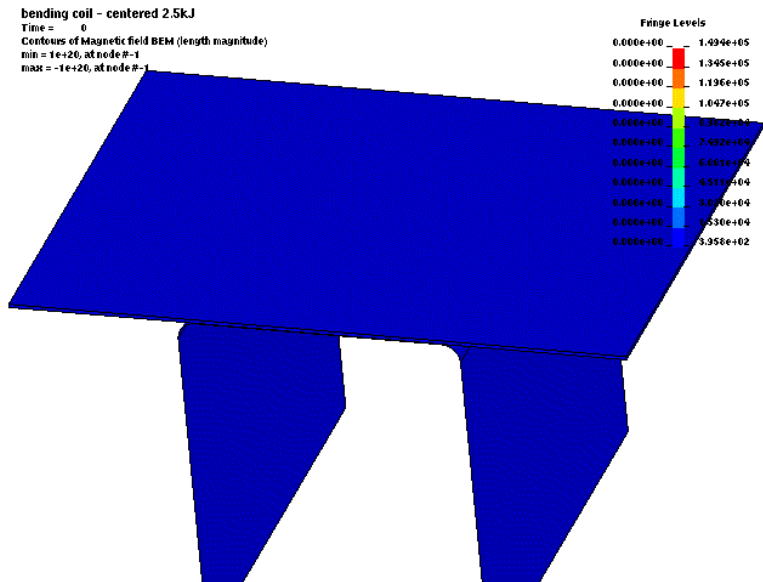
Mesh (general view)



Scalar potential on coil



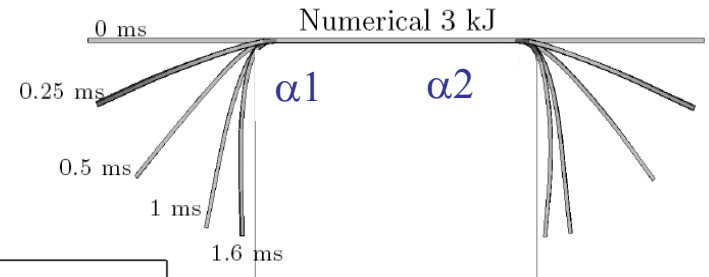
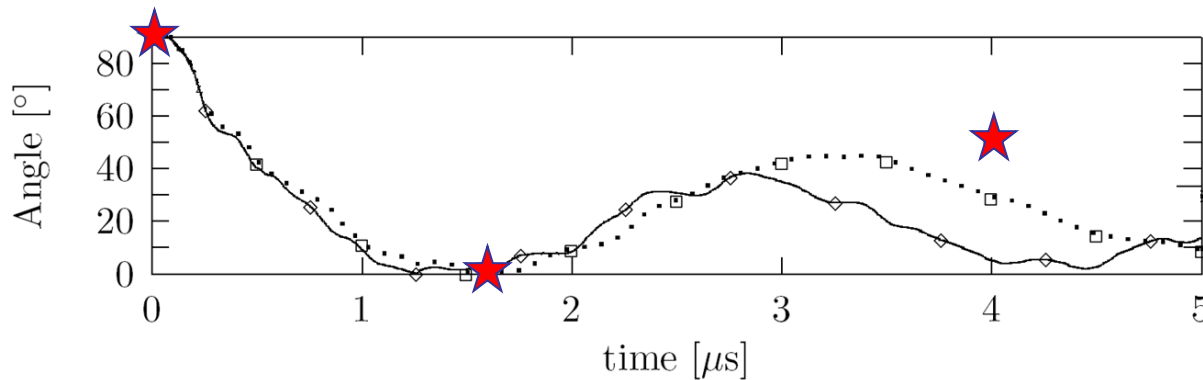
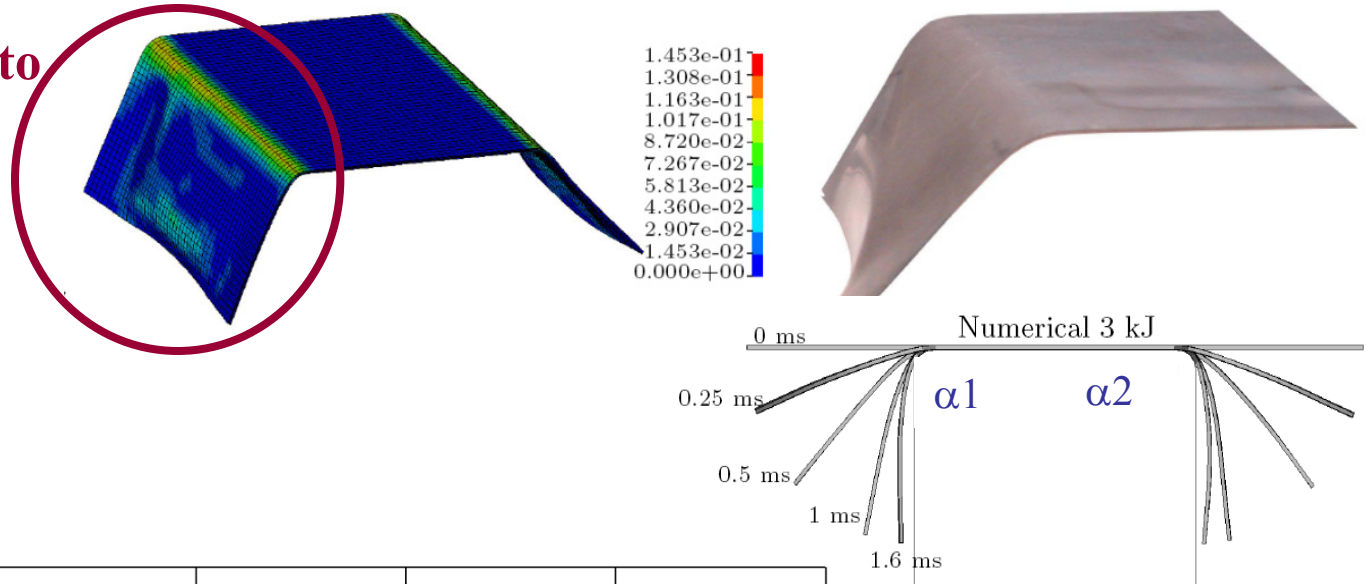
Sheet current density



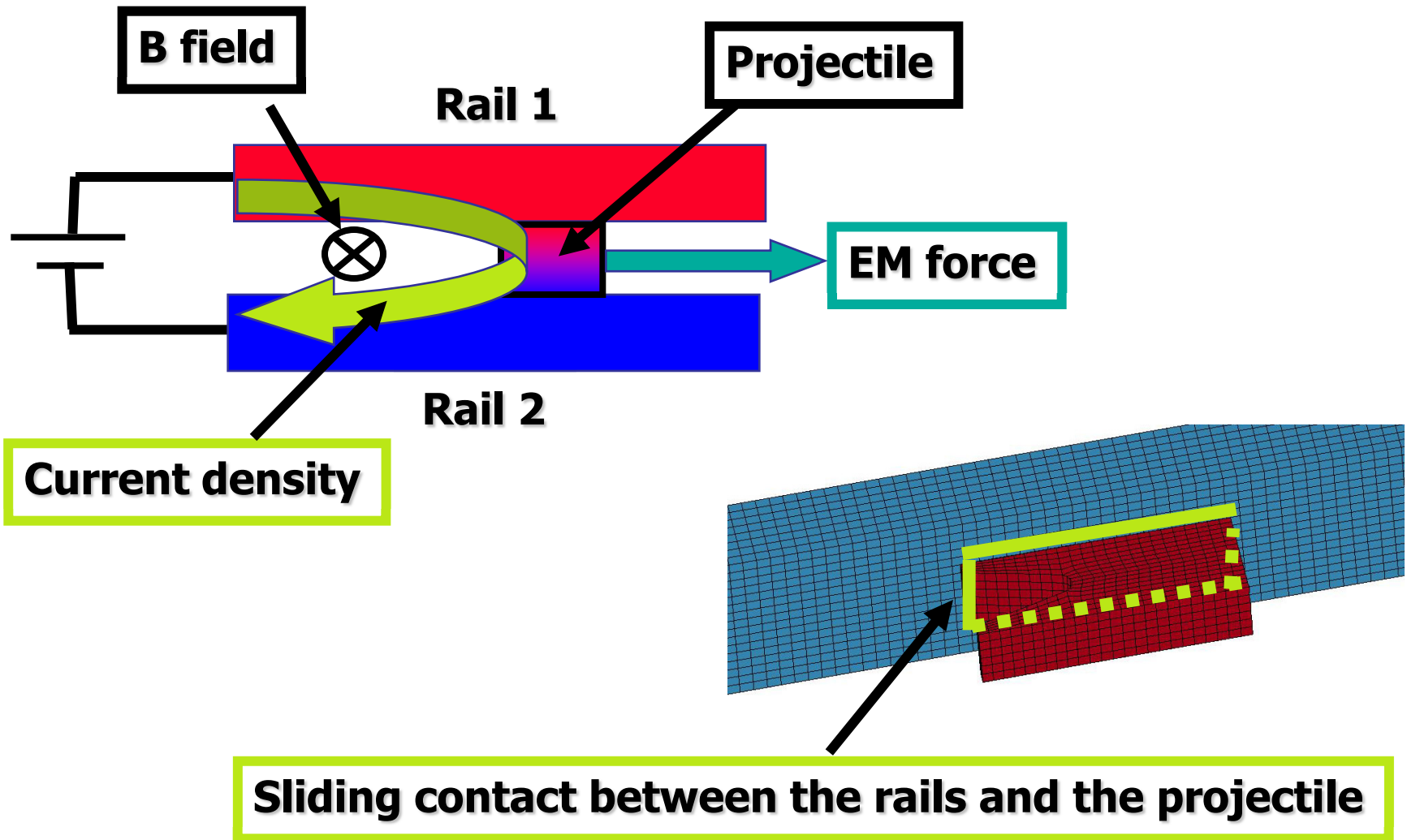
B field

Experimental vs numerical comparisons

Non homogeneous deformation due to induced currents



- ★ Experimental
- ◇— Simu α 1
- Simu α 2



- ◆ MPP version of the EM module allows sharing memory and CPU between processors, hence faster computations on larger cases.
- ◆ Future developments (pre-conditioners,...) should allow even better scaling.
- ◆ Recent EM contact capability allows rail gun like applications.
- ◆ LS-DYNA with EM module available as a “beta” version called “ls980”.

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